

FINAL PROJECT

DFX Expanded Hyperbolic Cordic Implementations

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OUTLINE:

- ❖ Objectives
- ❖ Status Summary
- ❖ Project Timeline
- ❖ Extended Hyperbolic Cordic in Math
- ❖ DFX VHDL Design
- ❖ Error Analysis
- ❖ IP Package and Peripherals
- ❖ Attention Areas





Objectives

- The original hyperbolic CORDIC (Coordinate Rotation Digital Computer) algorithm imposes a limitation to the input's domain which renders the algorithm useless for certain applications (**limited convergence**).
- A fixed-point implementation of the hyperbolic CORDIC algorithm with the expansion scheme proposed by Hu is presented, Using the *Iterative* Architecture, which is upgraded to a DFX Version.
- We used DFX because it combines the simplicity of a fixed-point system with the wider dynamic range offered by a floating point system. Using a single bit exponent which selects two different fixed-point representations, it allows dynamic scaling of signals throughout the system.



Status Summary

- The project is done on time as scheduled.



Project Timeline

Project # 1 - Phase A			2015												2016						
Activity	Notes	Status	9/5	10/28	11/4	11/11	11/18	11/25	11/30	12/9	12/5	12/10	12/30	1/6	1/13	1/20	1/27	2/3	2/10	2/17	
Start																					
Project Selection		Done																			
MATLAB implementations for FX		Done																			
MATLAB implementations for Expanded FX		Done																			
Implementation																					
VHDL implementations for FX		Done																			
VHDL implementations for Expanded FX		Done																			
DFX Design																					
Design DFX Barrel Shifter		Done																			
Design DFX Add/Sub		Done																			
Parametrization		Done																			
Run full range test case		Done																			
Write final report		Done																			



Extended Hyperbolic Cordic in Math

The method proposed by Hu consists in the inclusion of additional iterations for negative indexes i :

For $i \leq 0$

$$\begin{aligned}X_{i+1} &= X_i + \delta_i \left(1 - 2^{i-2}\right) Y_i \\Y_{i+1} &= Y_i + \delta_i \left(1 - 2^{i-2}\right) X_i \\Z_{i+1} &= Z_i - \delta_i \tanh^{-1} \left(1 - 2^{i-2}\right)\end{aligned}$$

For $i > 0$

$$\begin{aligned}X_{i+1} &= X_i + \delta_i Y_i 2^{-i} \\Y_{i+1} &= Y_i + \delta_i X_i 2^{-i} \\Z_{i+1} &= Z_i - \delta_i \tanh^{-1} \left(2^{-i}\right)\end{aligned}$$



Extended Hyperbolic Cordic in Math –Cont.

Depending on the mode of operation, the quantities X, Y and Z tend to the following values, for sufficiently large N :

Rotation Mode	Vectoring Mode
$x_n = A_n(x_1 \cosh z_1 + y_1 \sinh z_1)$ $y_n = A_n(y_1 \cosh z_1 + x_1 \sinh z_1)$ $z_n = 0$	$x_n = A_n \sqrt{x_1^2 - y_1^2}$ $y_n = 0$ $z_n = z_1 + \tanh^{-1}(y_1/x_1)$

$$A_n \leftarrow \left[\prod_{i=-M}^0 \sqrt{1 - (1 - 2^{i-2})^2} \right] \left[\prod_{i=1}^N \sqrt{1 - 2^{-2i}} \right]$$

Range of convergence with respect to the negative iterations (M):

M	$\theta_{\max}$ from (19)	M	$\theta_{\max}$ from (19)
0	2.09113	5	12.42644
1	3.44515	6	15.54462
2	5.16215	7	19.00987
3	7.23371	8	22.82194
4	9.65581	9	26.98070
		10	31.48609

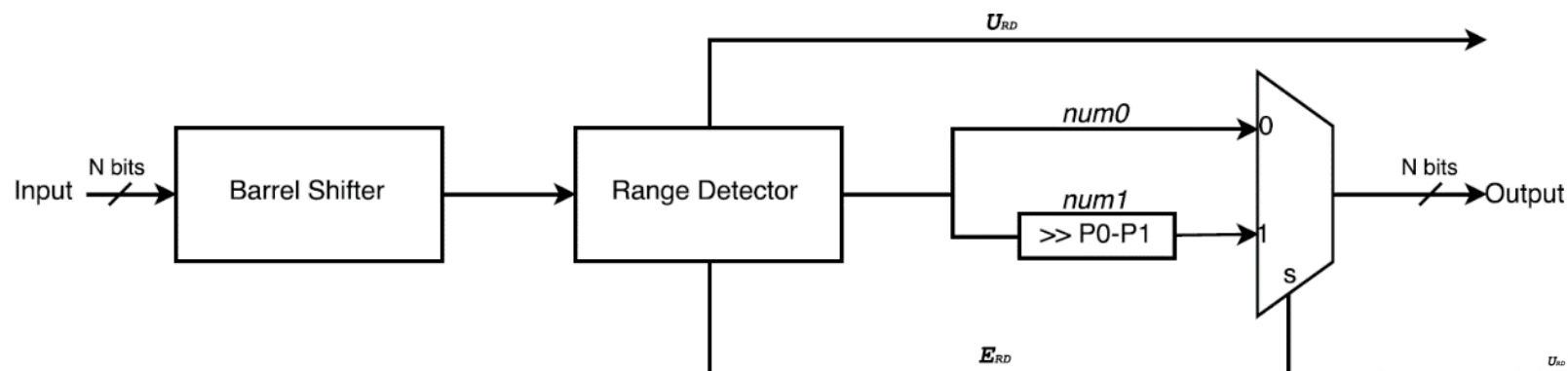
$$\theta_{\max} = \sum_{i=-M}^0 \tanh^{-1}(1 - 2^{i-2}) + \left[\tanh^{-1}(2^{-N}) + \sum_{i=1}^N \tanh^{-1}(2^{-i}) \right]$$

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DFX Barrel Shifter

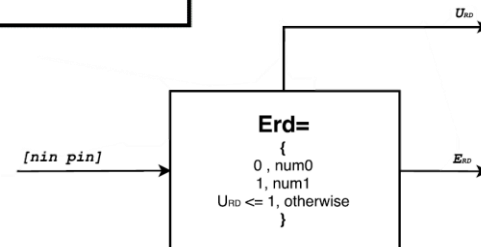


Range Detector:

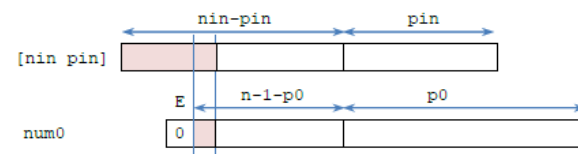
□ It determines whether a fixed point (FX) number $[n_{in} \ p_{in}]$ can be represented as a DFX $num0$ number with n bits. Note that if $E=1$, it does not necessarily mean that it is a $num1$ number with n bits, because it might actually need more than n bits.

□ For the DFX number to be $num0$ with n bits, the corresponding FX number has to be such that the $n_{in}-p_{in}-(n-1-p_0)+1$ MSBs have to be all 1 or 0 (due to sign extension). This means only one of those bits is needed.

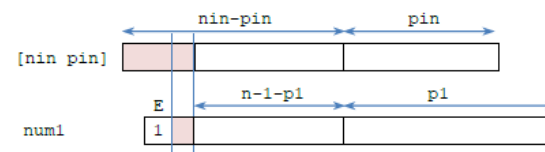
□ The figure assumes that: $n_{in}-p_{in} \geq n-1-p_0, p_0 \geq p_{in}$. If $n_{in}-p_{in} < -1-p_0$ then the FX number is a $num0$ DFX number with n bits. If $p_0 < p_{in}$, we need to get rid of p_0-p_{in} LSBs (we lose precision here).



$$E_{RD} = \overline{b_{n_{in}-p_{in}-1} \cdots b_{n-1-p_0-1}} + \overline{b_{n_{in}-p_{in}-1} \cdots b_{n-1-p_0-1}}$$



If not, we try with $num1$:



If not, it means we need more than n bits.



Error Analysis

- To measure the accuracy of the implemented DFX hyperbolic CORDIC, error analysis is performed on a different cases that will cover the two formats in the DFX representation (num0, num1).
- The results are compared with the ideal values obtained in MATLAB.
- The error measures will be:

$$\textit{Relative Error} = \frac{| \textit{ideal value} - \textit{DFX CORDIC value} |}{| \textit{ideal value} |}$$

$$\textit{SNR} = 20 * \log_{10} \frac{| \textit{ideal value} |}{| \textit{ideal value} - \textit{DFX CORDIC value} |}$$



Format & Range

- **Format:** $[n \ p0 \ p1]$

- X,Y format [32 29 25]
- Z format [32 27 25]

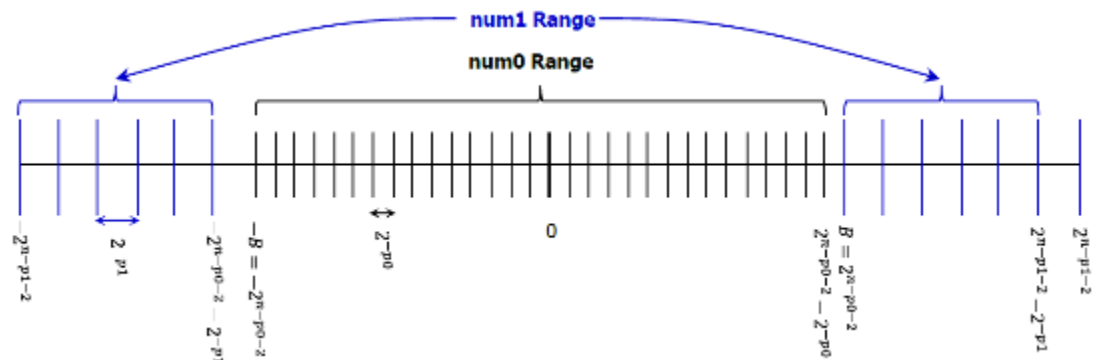
- **Range**

- X,Y:

- Num0 : $[-2,2)$
- Num1 : $[-32,-2) \cup [2,32)$

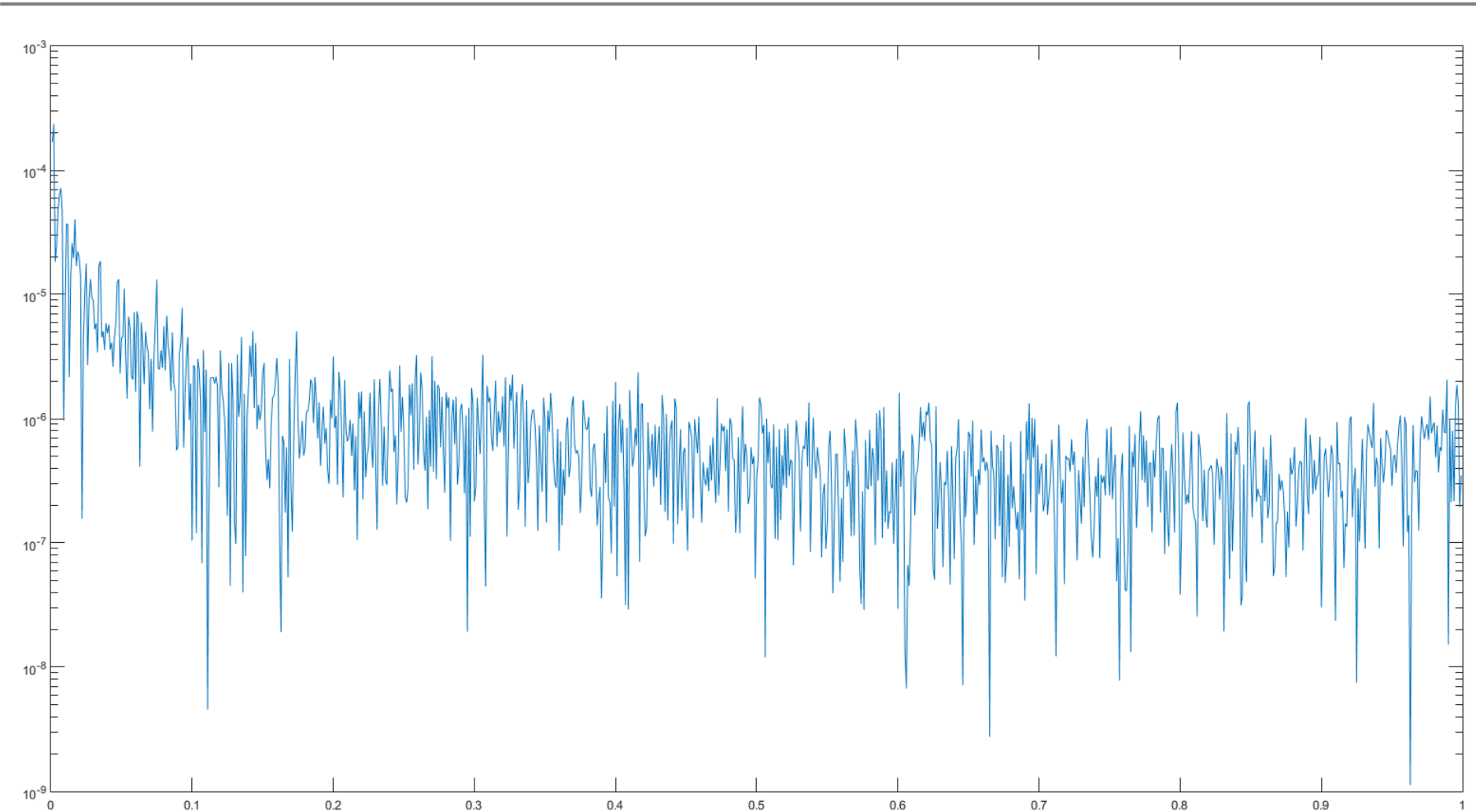
- Z:

- Num0 : $[-8,8)$
- Num1 : $[-32,-8) \cup [8,32)$



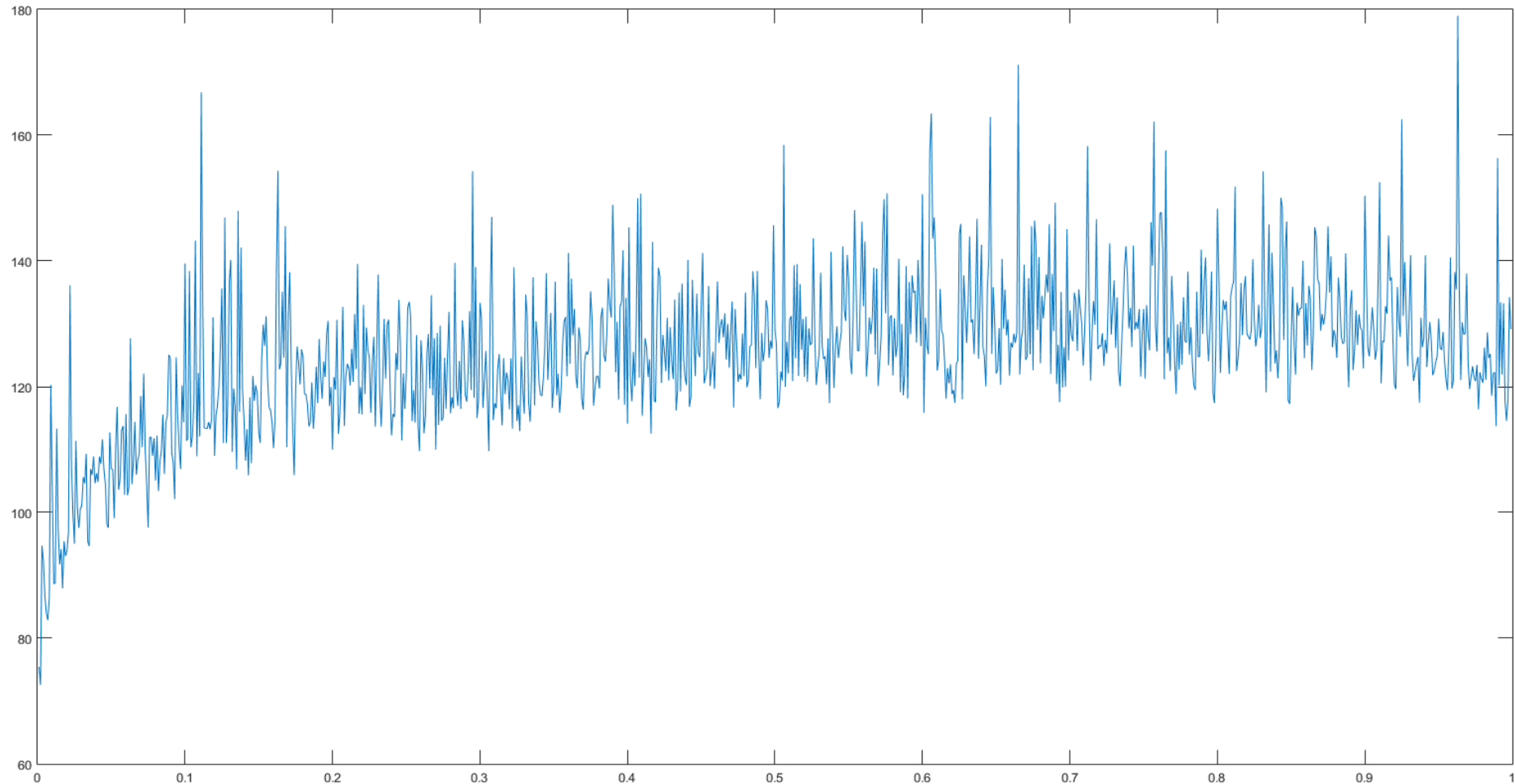


Results-**Atanh**-Relative error [0 1) 1000 inputs



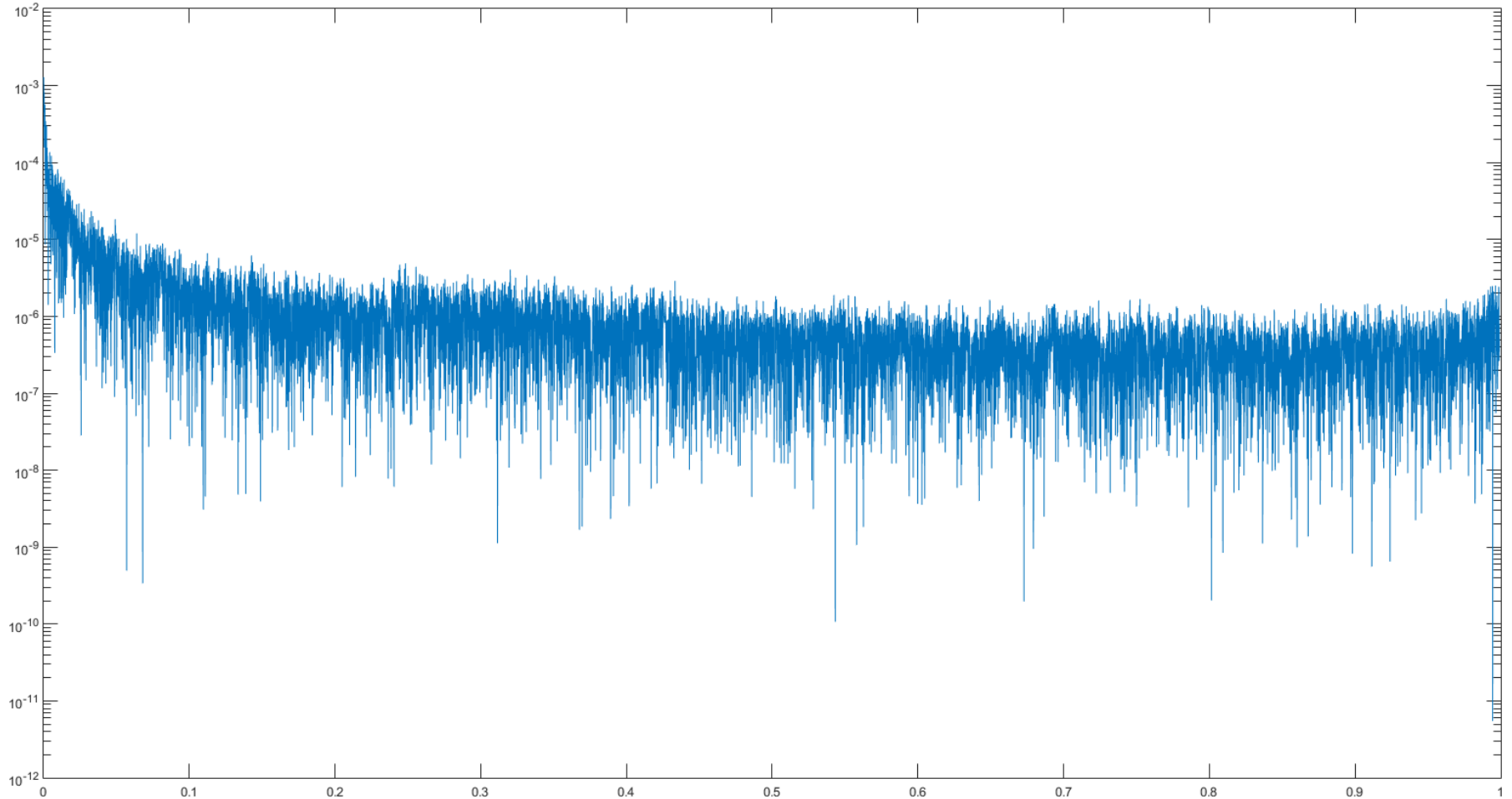


Results-**Atanh**-SNR [0 1) 1000 inputs



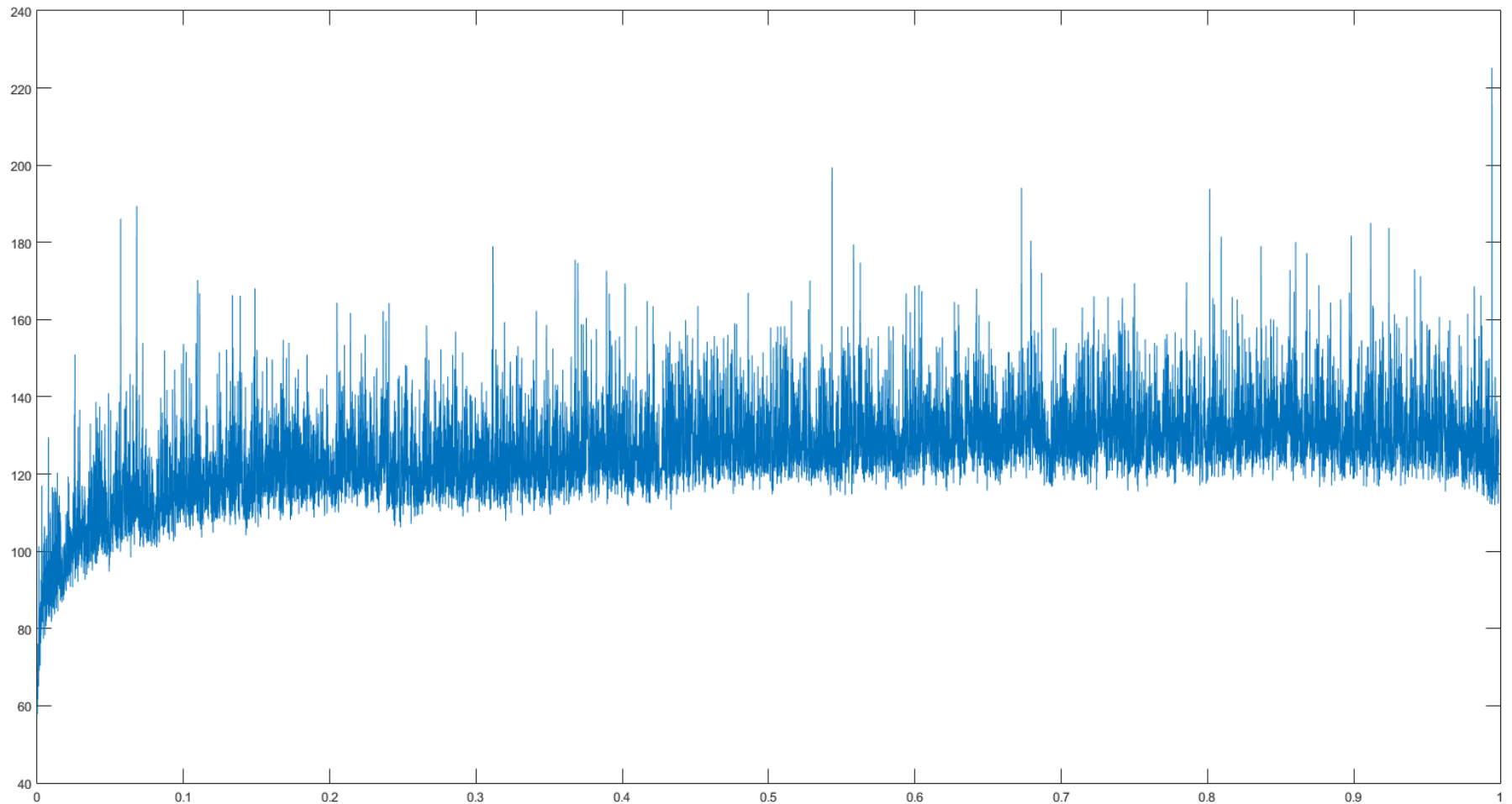


Results-**Atanh**-Relative error [0 1) 10000 inputs



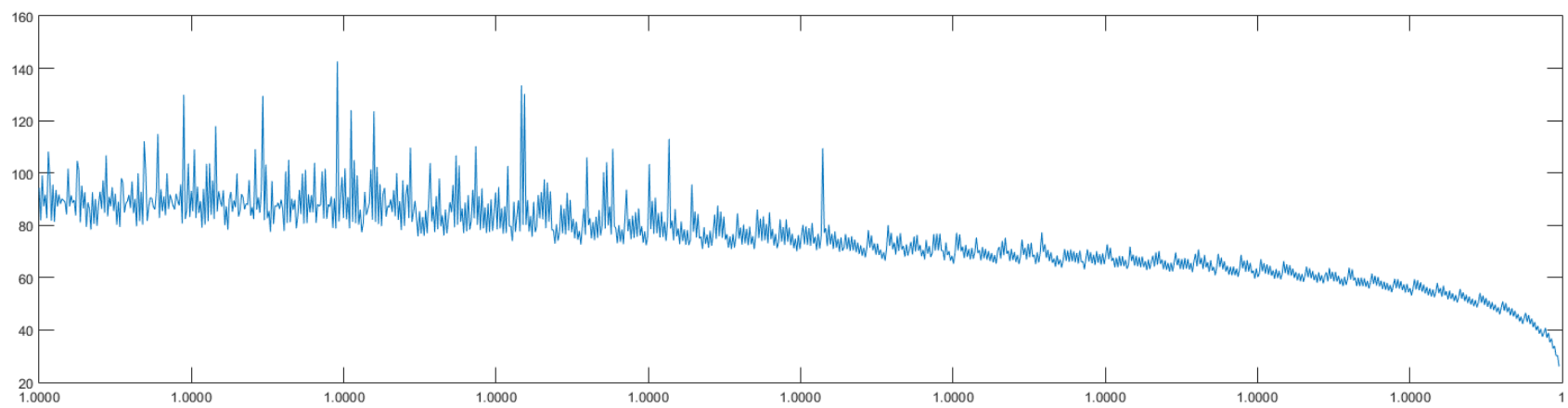
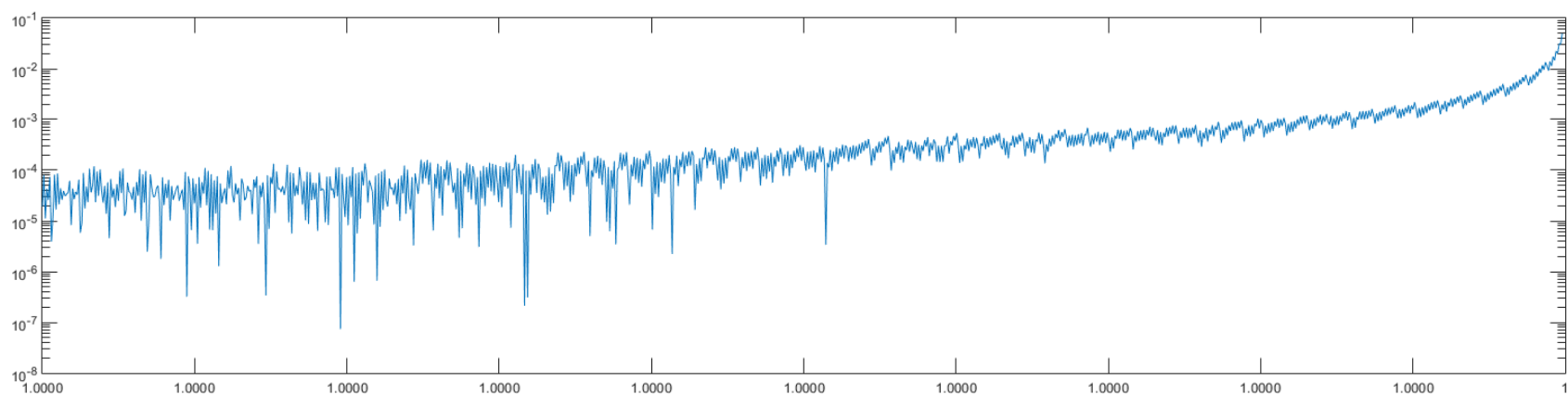


Results-**Atanh**-SNR [0 1) 10000 inputs



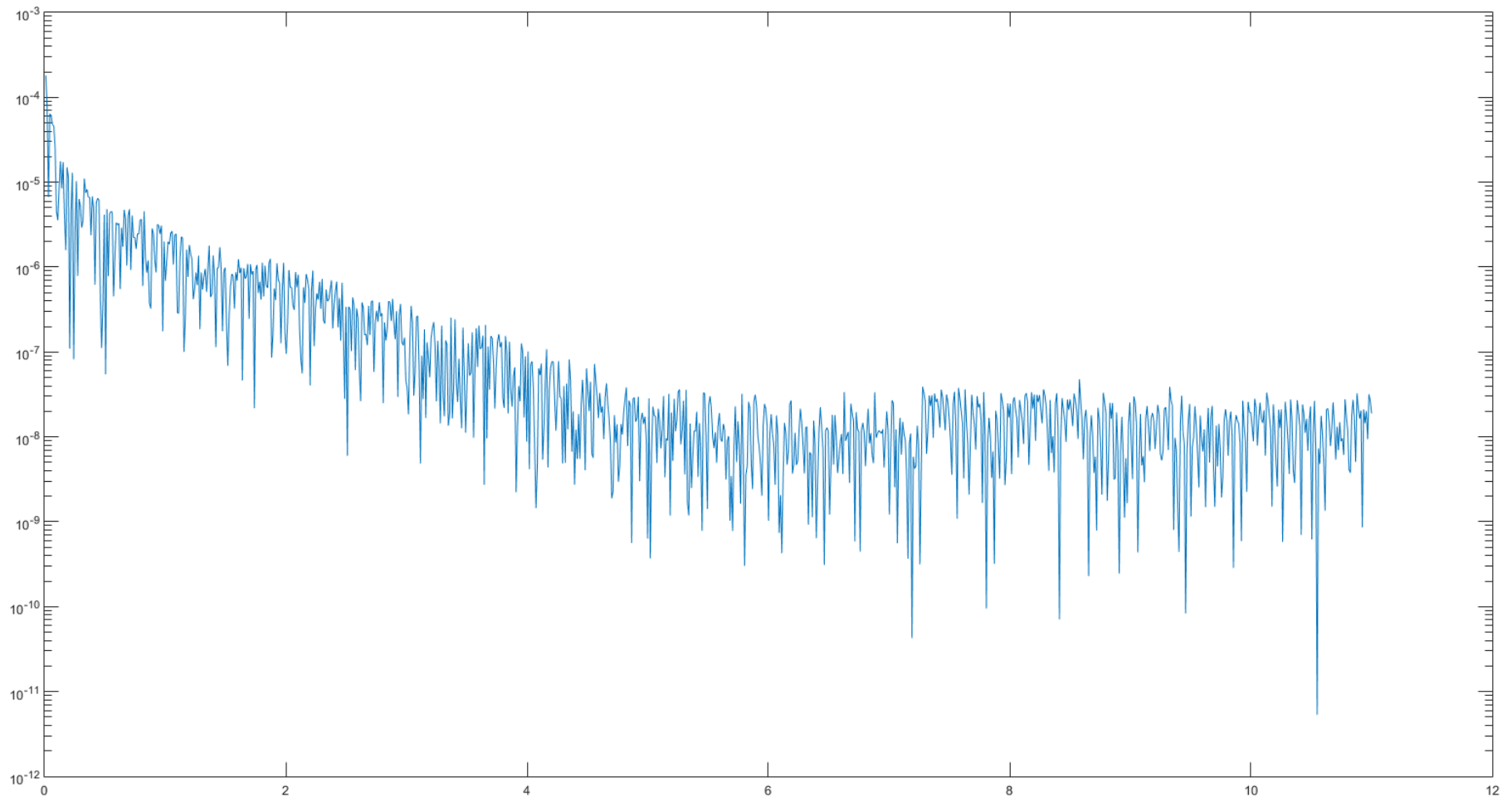


Results-**Atanh**-Relative error and SNR (0.999999 to 0.999999998)



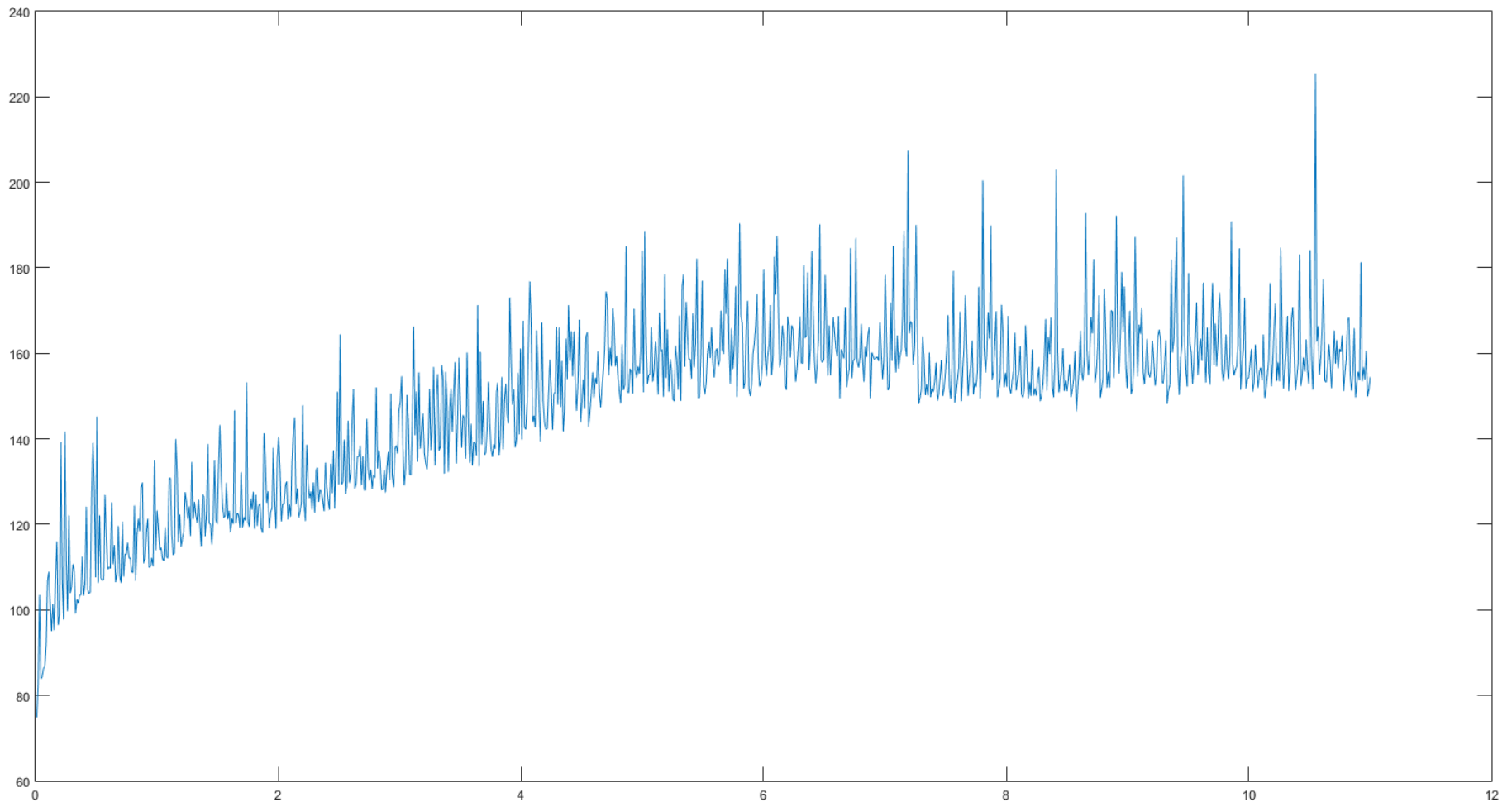


Results-Sinh-Relative error [0 11] 1000 inputs



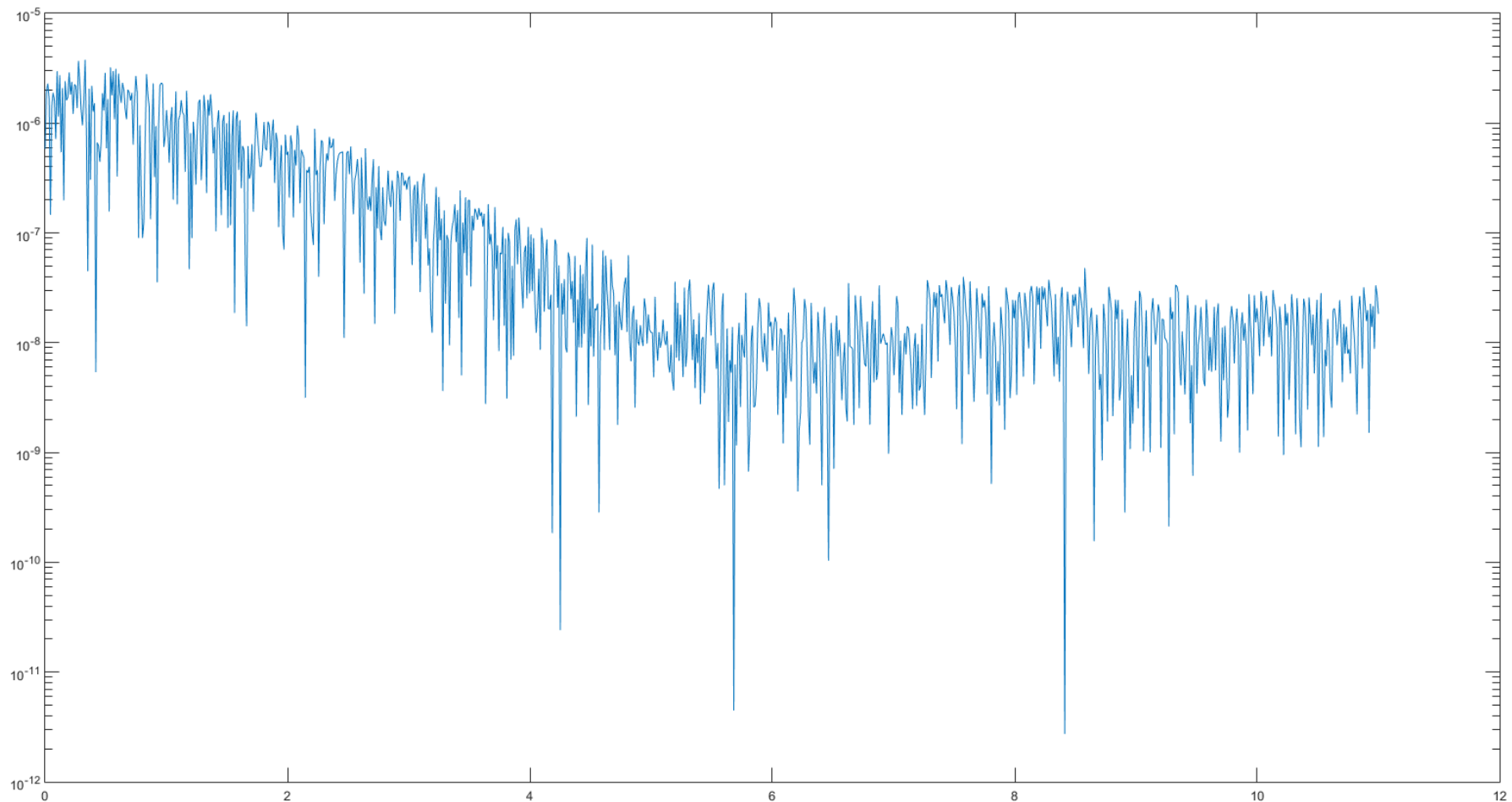


Results-**Sinh**-SNR [0 11] 1000 inputs



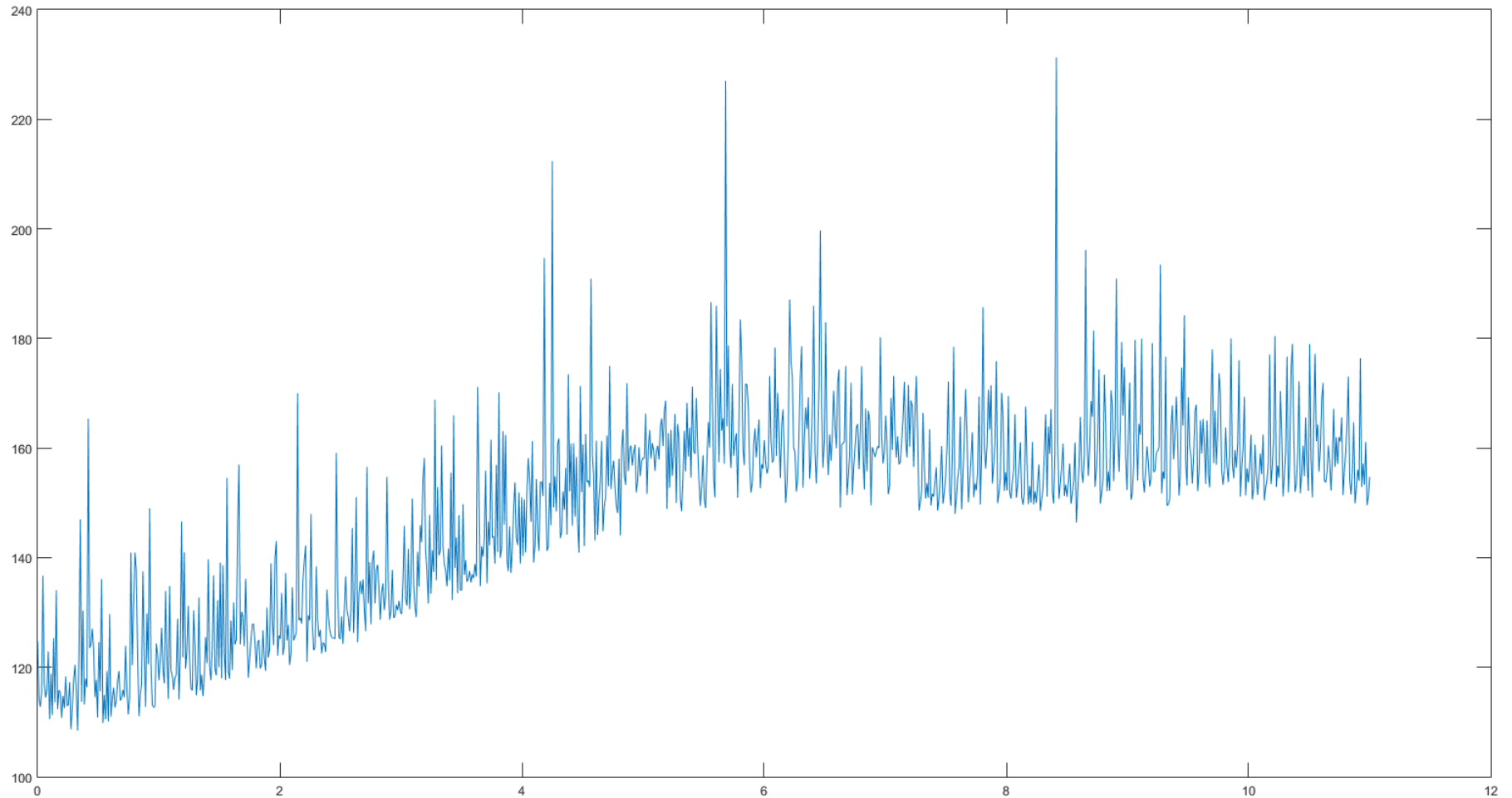


Results-**Cosh**-Relative error [0 11] 1000 inputs



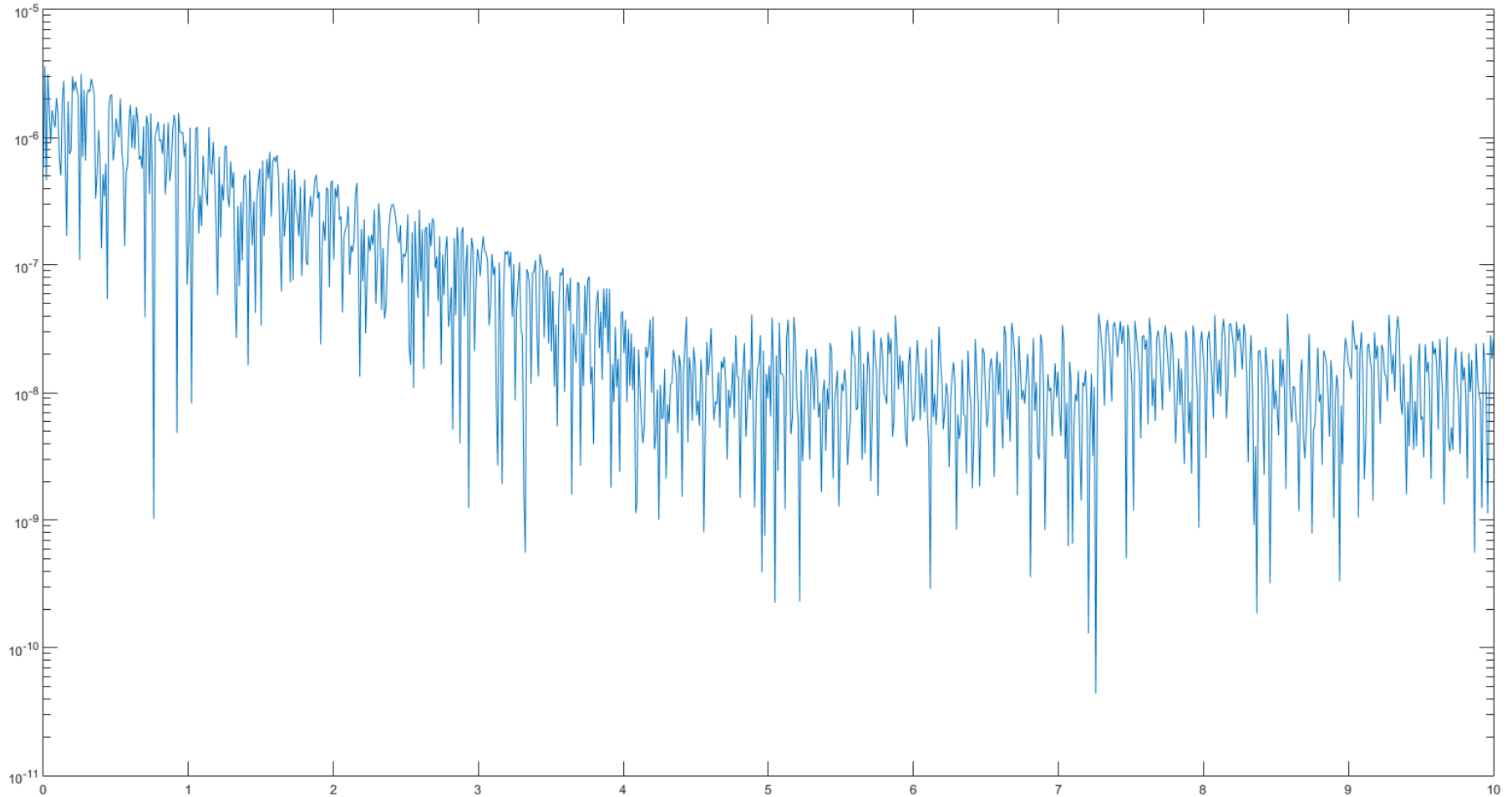


Results-**Cosh**-SNR [0 11] 1000 inputs



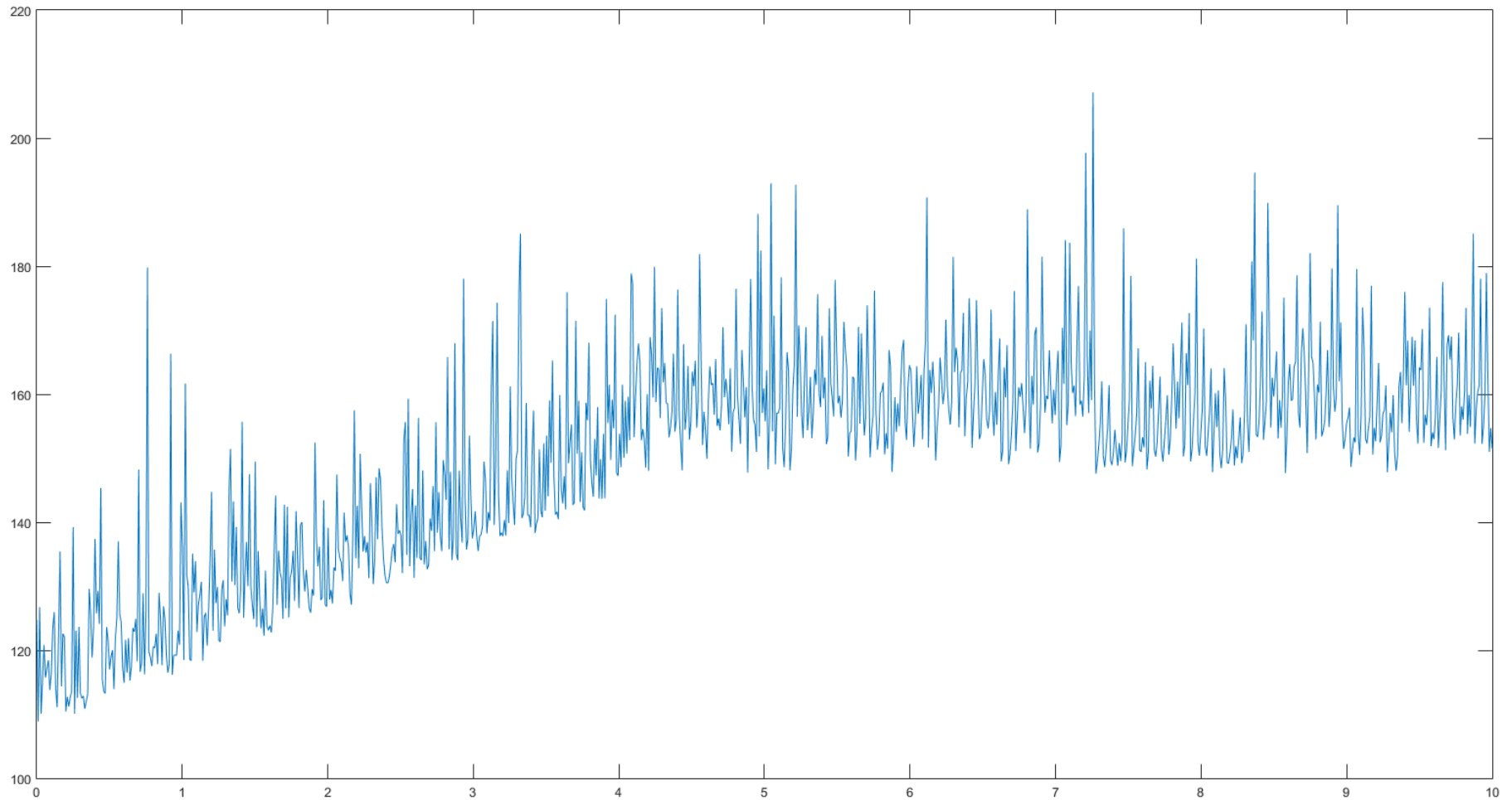


Results-**Exp**-Relative error [0 10] 1000 inputs



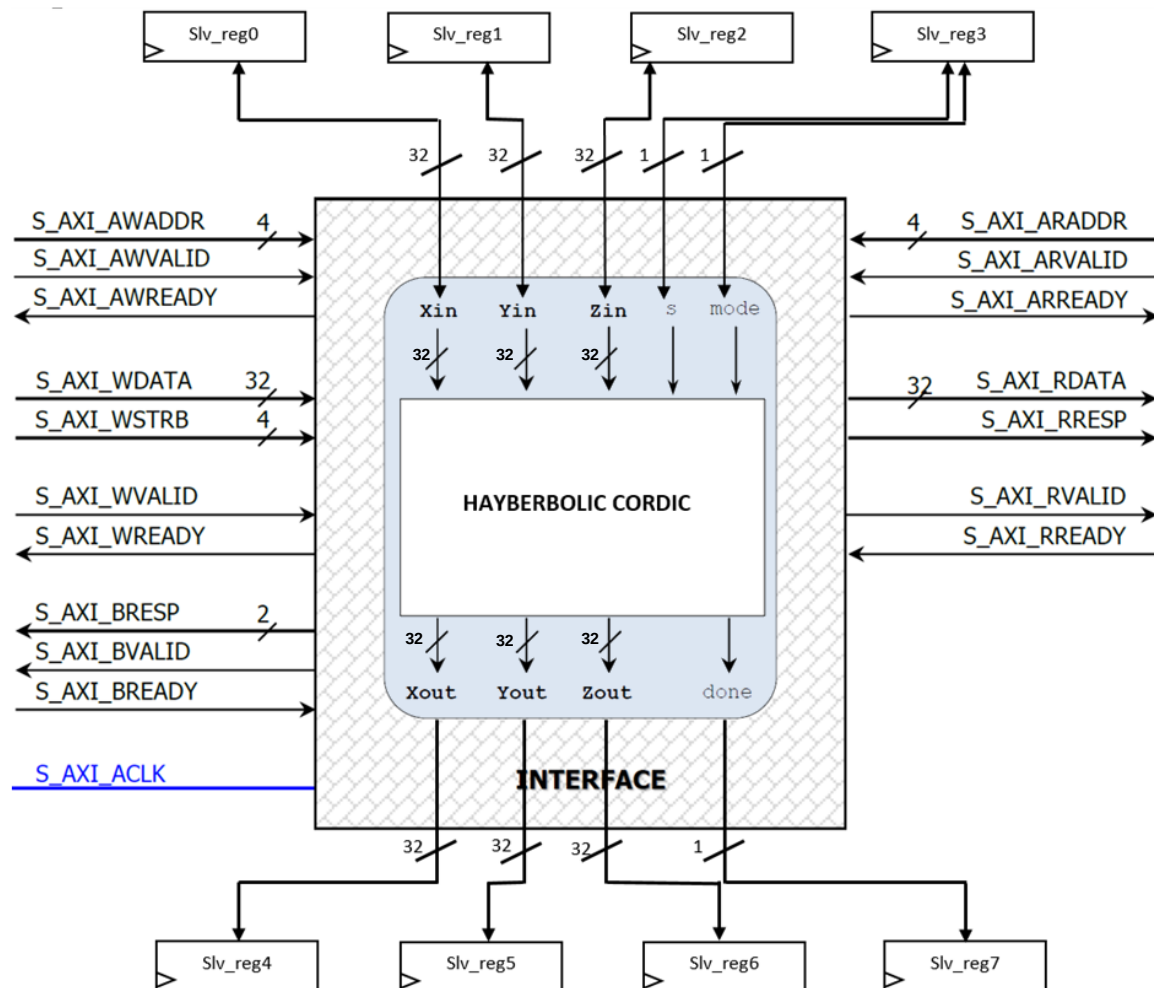


Results-**Exp**-SNR [0 10] 1000 inputs



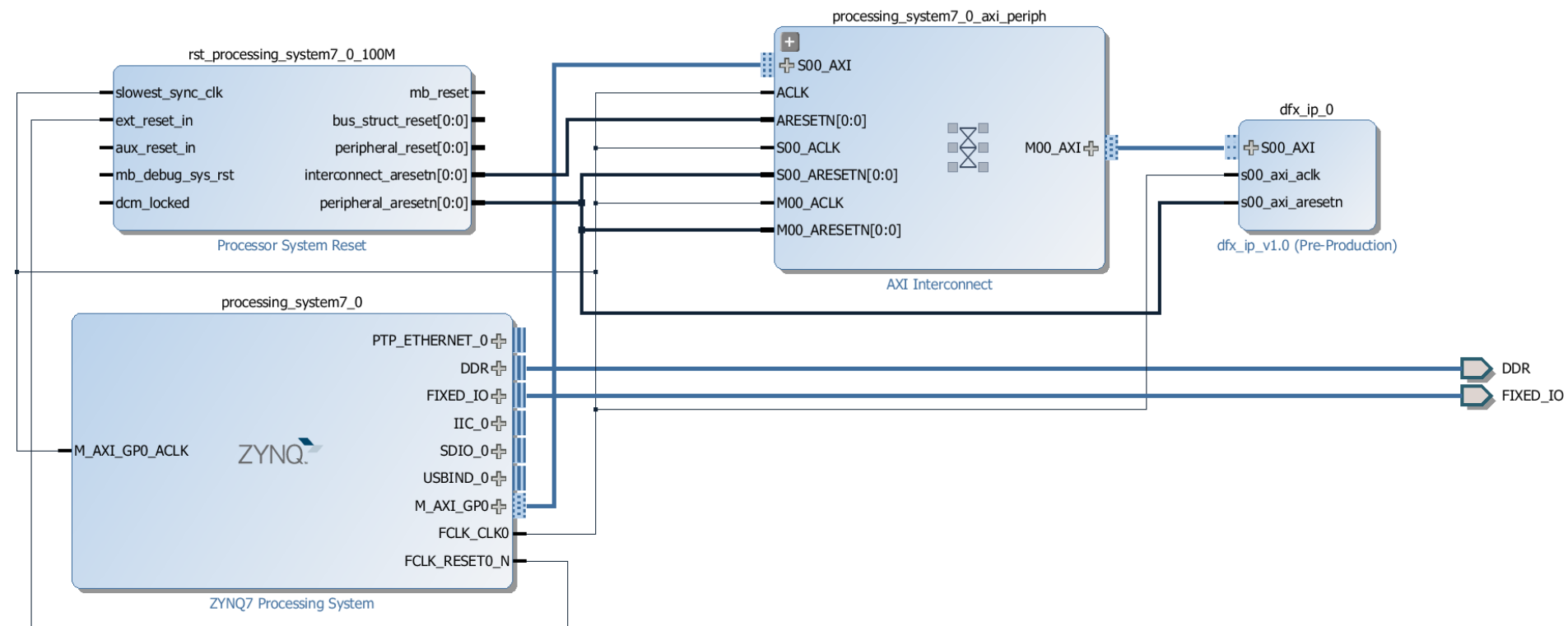


IP Package and Peripherals





IP Package and Peripherals





Attention Areas

- Number of Iterations (positives and negatives).
- DFX format used.
- Irregularity due to:
 - Truncation of P0-P1 LSB bits when doing DFX Addition/Subtraction. Can be recovered.
 - Converting *Decimal* numbers to *Binary* and vice versa.



References

- X. Hu, R.G. Harber, S.C. Bass, “Expanding the range of convergence of the CORDIC algorithm,” *IEEE Transactions on Computers*, vol. 40, no. 1, pp. 13-21, Jan. 1991.
- J. Becker, M. Platzner, S. Vernalde (Eds.): FPL 2004, LNCS 3203, pp. 200–208, 2004. c Springer-Verlag Berlin Heidelberg 2004.
- *D. Llamocca, C. Agurto*, “A FIXED-POINT IMPLEMENTATION OF THE EXPANDED HYPERBOLIC CORDIC ALGORITHM” *Lat. Am. appl. res. v.37 n.1 Bahía Blanca ene. 2007*.



Thank You

- Any Questions??