

# Morphology Operations

## Exploring TBB and Pthreads

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**Abstract**—The purpose of this project is to explore how TBB and pthreads can impact execution speed.

### I. INTRODUCTION

The motivation behind this project is to determine the impact of different parallelization strategies. We will also explore how different aspects will change timings. This will include different sized structural element, amount of threads, picture size and hardware.

### II. METHODOLOGY

#### A. Structuring Element

A structuring element is the neighborhood of where we apply the morphological operation. The center of the structuring element will contain the input pixel of which the operation is being done. For the morphological operations we will be using a disk with radius 2 as well as radius 1. The mask that is applied we can call a kernel. This mask is hard coded into the cpp file. There is a switch available to determine if you want to use a disk size 1 or 2.

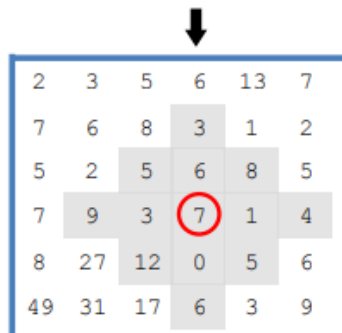
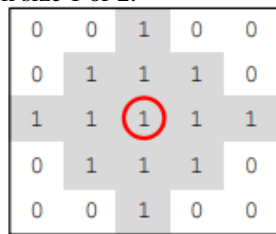


Figure 1: Structuring Element

#### B. Erosion

Erosion involves taking the minimal value of the image over the structuring element.

#### C. Dilation

Dilation involves taking the maximum value of the image in the structuring element.

#### D. Opening

Opening is when you do erosion followed by dilation. Opening is used for breaking narrow elements and eliminating small noise [2].

#### E. Closing

Closing is the opposite of opening in the sense that it should be dilation followed by erosion. Closing involves smoothing boundaries to join narrow breaks and small holes caused by noise. [2]

#### F. Boundary Extraction

Boundary extraction can be done as a inner boundary or an outer boundary extraction. To do an inner boundary you need to take the original image and subtract the eroded image. To do a outer boundary you need to take a dilated image – original image. Both of these operations have been explored in this project.

## G. Main Program Flow

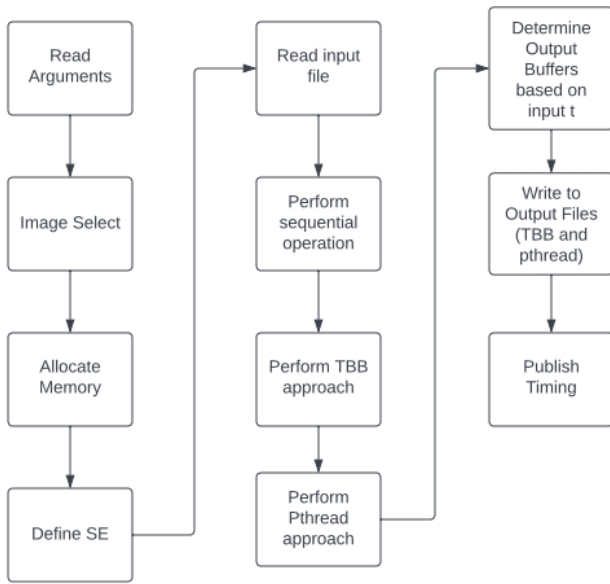


Figure 2: Main Program Flow Chart

The main program flow starts by reading elements that have been input by the user. This will be input initially when calling the program. There are four input elements. The first element is which morphology operation is needing to be performed. This can be a value from 1 – 6. Dilation is 1, erosion is 2, opening is 3, closing is 4, inner boundary extraction is 5, and finally outer boundary is 6.

The second input argument is an image selector. Since four images were used in the project this allows you to swap between the images. However, the input.bif needs to be updated before running again. This switch simply changes column and row values to account for different sized images. Now parameter 3 is the size of structuring element, this can be a 1 or a 2. Finally the last parameter is how many cores to launch for the pthread implementation.

The next steps in the program flow include allocating the memory for the tbb and pthreaded applications. We then define the values of SE based on the input parameters. Next we read in the input file into both the TBB and pthread buffers. The parallelization methods are then invoked. In order to write to the output image buffers we look at which operation was requested. This is due to the fact that some of these operations take two operations to complete. Thus it changes which buffer has the final output. The software uses O and O2 and buffers. In the case of opening for example we do erosion and store the results in O. Then we do dilation with the input to dilation being O. The output is then O2. So based on this information we will write O2 to the output file. The last part of the program flow is to publish the timing for sequential, tbb, and pthread implementation.

```

robert@robert-Cedar-Trail-Client-platform:~$ ./morpho 6 4 2 50
(read_binfile) Input binary file 'uchip.bif': # of elements read = 20672000
(read_binfile) Size of each element: 1 bytes
(read_binfile) Input binary file 'uchip.bif': # of elements read = 20672000
(read_binfile) Size of each element: 1 bytes
(write_binfile) Output binary file 'Outputtbb.bof': # of elements written = 2067
2000
(read_binfile) Size of each element: 1 bytes
(write_binfile) Output binary file 'Outputp.bof': # of elements written = 206720
00
(read_binfile) Size of each element: 1 bytes
Sequential Approach:
  start: 570433 us      end: 111196 us
  Elapsed time (actual computation): 21540763 us
TBB Approach:
  start: 372095 us      end: 536789 us
  Elapsed time (actual computation): 11164694 us
Pthread Approach:
  start: 536790 us      end: 609965 us
  Elapsed time (actual computation): 8073175 us
robert@robert-Cedar-Trail-Client-platform:~$
  
```

Figure 3: Application call

The two parallelization approaches that were used were TBB and pthreads. TBB was done by using nested parallel for loops. These were done along the lines of sX and sY. sX and sY are simply the rows and columns of the image. So, this allows each pixel to get the operation be completed in parallel. Now, for some operations it would take launching two separate parallel\_for operations. For example in the case of opening you needed to perform erosion before dilation. So we would launch the parallel\_for loops for erosion. Once all of these were complete then we would do the dilation of the output image from the dilation.

For the pthread approach threads were launched based off of columns from an image. Based on the number of threads an upper and lower bound would be calculated for each thread. This upper and lower bound would define how much of the image each thread would be responsible for. This essentially made the image into strips that each thread would take care of each row in those columns. Like TBB if there was a multi operation then we would need to launch the threads and wait for them all to complete or merge. After this, we would launch new threads for the second operation.

## III. EXPERIMENTAL SETUP

The project is being ran on a DE2i-150 board. This board is running linux operating system. Data was collected for multiple amount of threads as well as structuring element. The same test was similarly done on a desktop PC running Ryzen 7 3700.

## IV. RESULTS

The results will use a MATLAB script much like the ones used in assignments during the course. It will compare the image tested in MATLAB with the output file from the board. A sum of differences will be presented to the user. The matlab script will also support taking a JPEG image and converting it to a greyscale image that way multiple images can be tested. This will allow us to see the impact of different sized images regarding the 3 different approaches as well. Some elements of the matlab script may need edited to check different parameters such as image need to change to the image you are checking and SE needs updated accordingly.

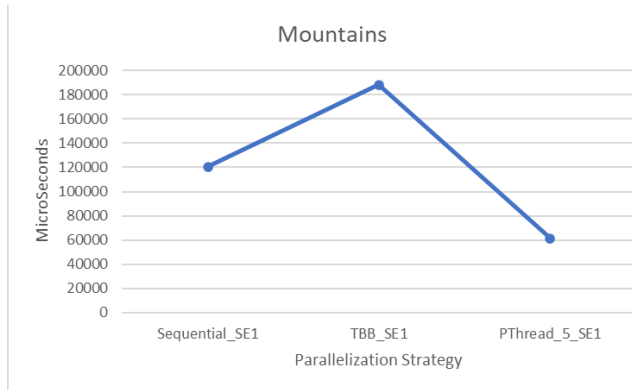


Figure 4: Mountains Dilation

We can see in figure 4 that TBB took slightly longer than the sequential approach for a relatively small image. This image was 600 x 400. For comparison sake of the three parallelization strategies we will use pthreads launching 5 threads. This is due to five threads being the best inflection point of time savings.

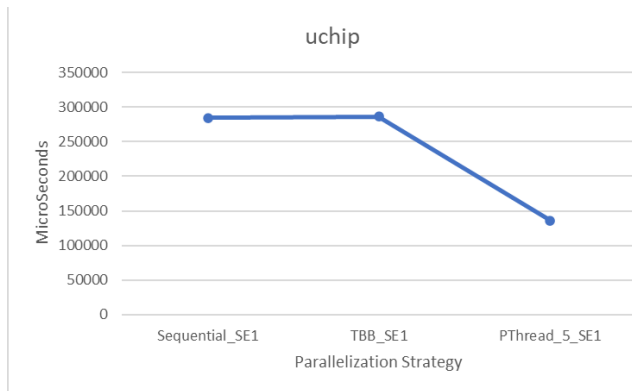


Figure 5: Uchip Dilation

In figure 5 we can see when we run a slightly larger image, 940 x 602 that there is some more benefit to TBB. The values are rather similar and seem to be only a slight gain. And in this case again pthreads is able to really give us a speed up.

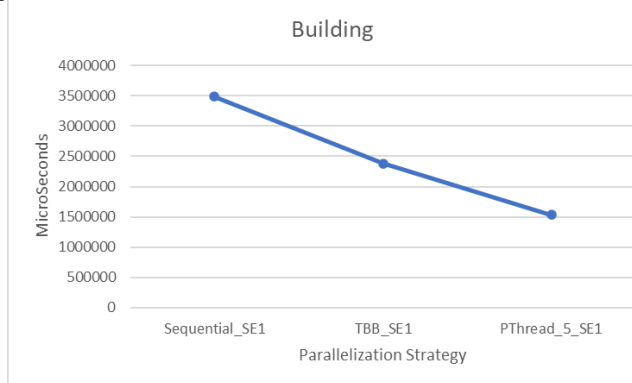


Figure 6: Building Dilation

For the building image the pixel count is 3472 by 2315. This is a considerable jump in pixel size compared to the previous two images. TBB now creates a significant time

savings. And here again we see that pthreads saves the most time.

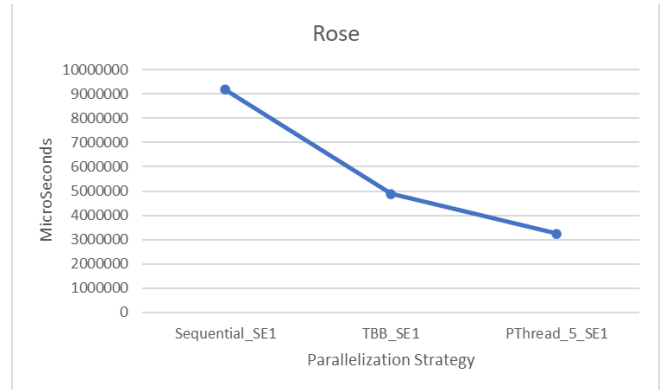


Figure 7: Rose Dilation

The final image is that of a rose that is coming in at 5168 by 4000 for the pixel count. Here we can see an even bigger jump in time savings for TBB. So it is safe to say as the image gets larger that TBB is able to see more and more benefits.

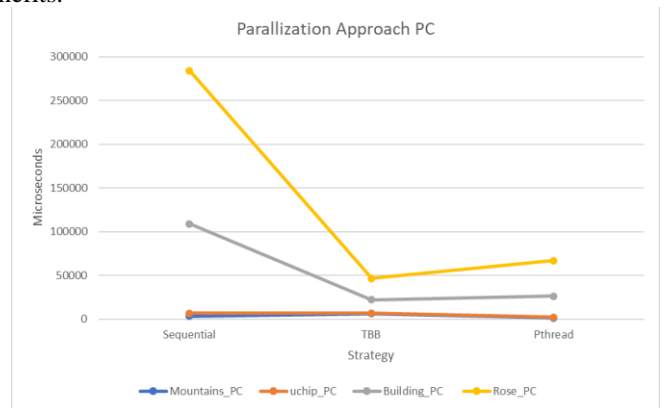


Figure 8: Parallelization on PC

The next point of comparison that was explored was that would these different strategies change if the hardware changed. It turns out that TBB had huge gains from extra resources available to the algorithm. This can be seen base on the differences of Figure 8 and Figure 9. Both of these operations were to do with dilation. Pthreads gained less by changing hardware than the TBB algorithm did.

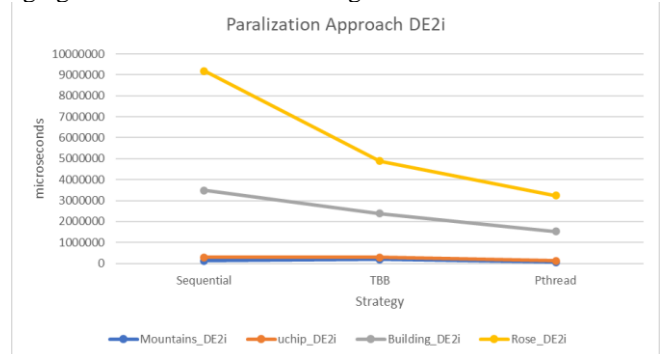


Figure 9: Parallelization on DE2i

