

ECE 2700

Fall 2017

Vhdl 4-Way Traffic Controller



Group members:

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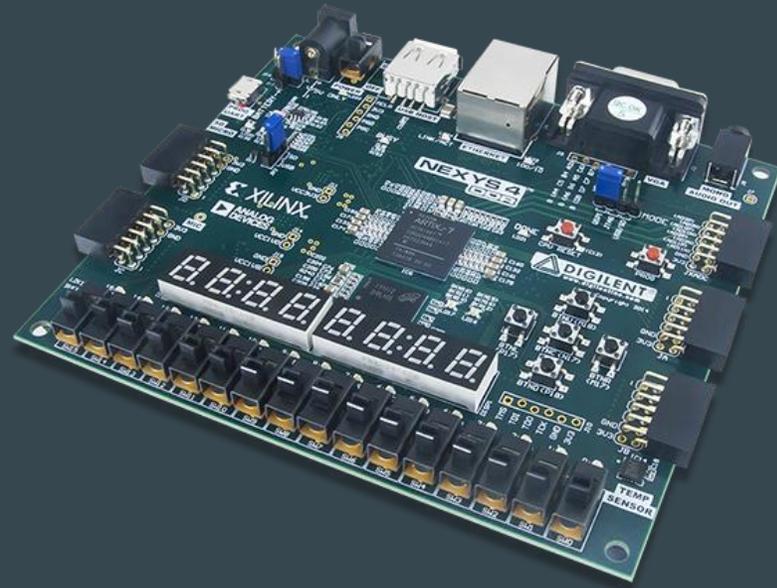
Allison Nguyen

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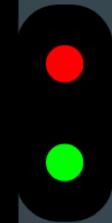
Agenda

- Concept
- Design Implementation
- Demo
- Improvement



Bill of Materials

- Nexys4 DDR board
- Bread board
- 20 LEDs (Red, yellow, green and blue)
- 20 Resistors



Concept

Use Nexys4 DDR to control the time of a 4-way traffic signal

Manually control crosswalk indicator.

Modify signal timing for heavy traffic.



Concept

Stop indicated by Red LED

Caution indicated by Yellow LED

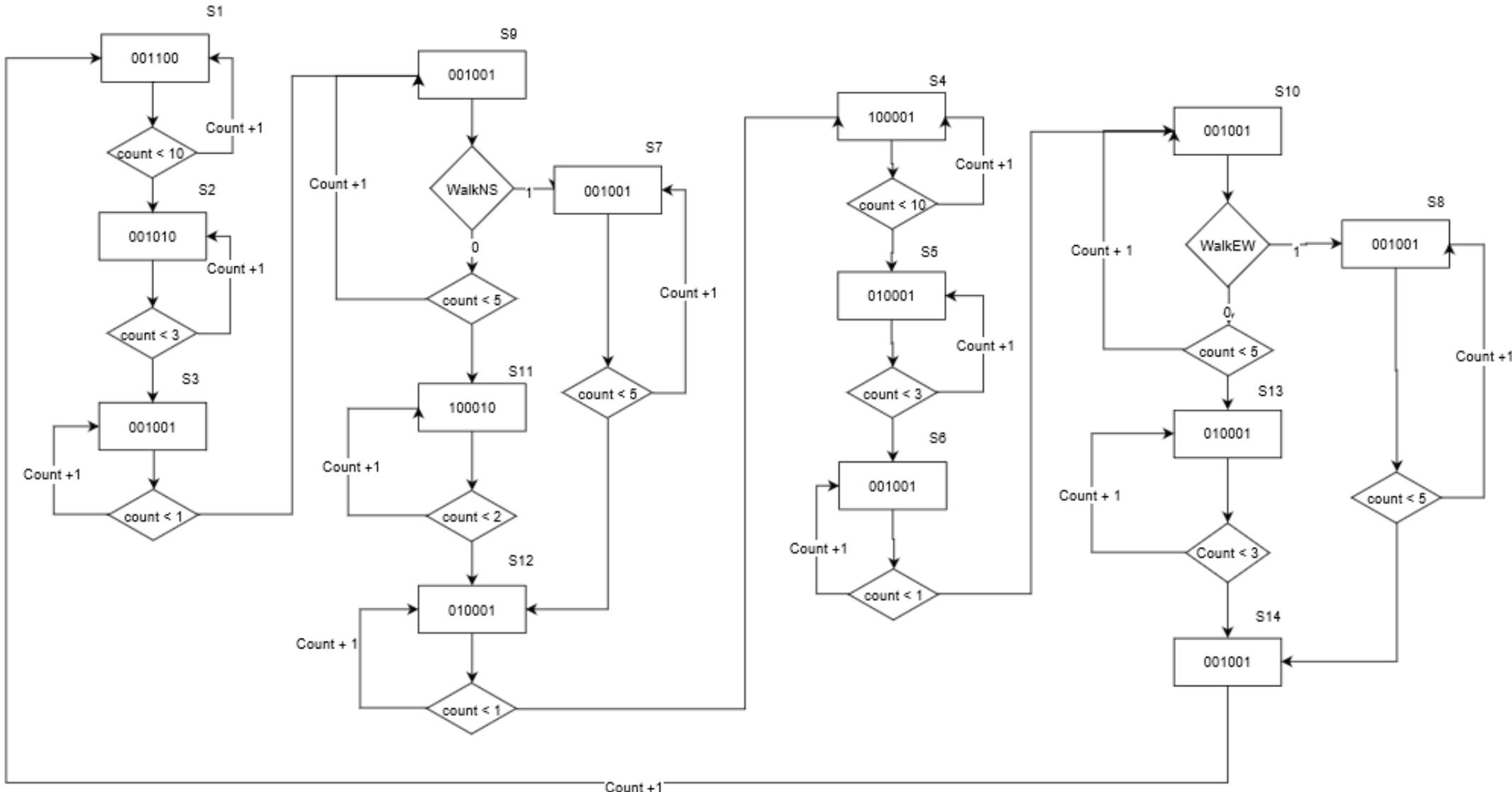
Go indicated by Green LED

Turn Left indicated by Yellow LED
(Flash when Red)

Walk indicated by Blue LED

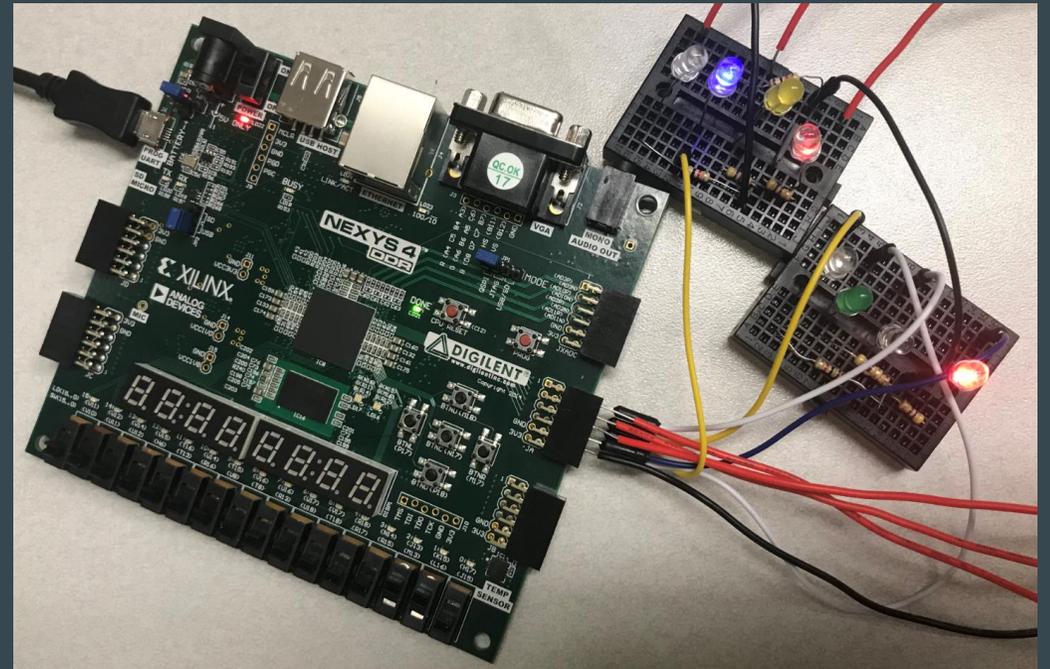


State Diagram



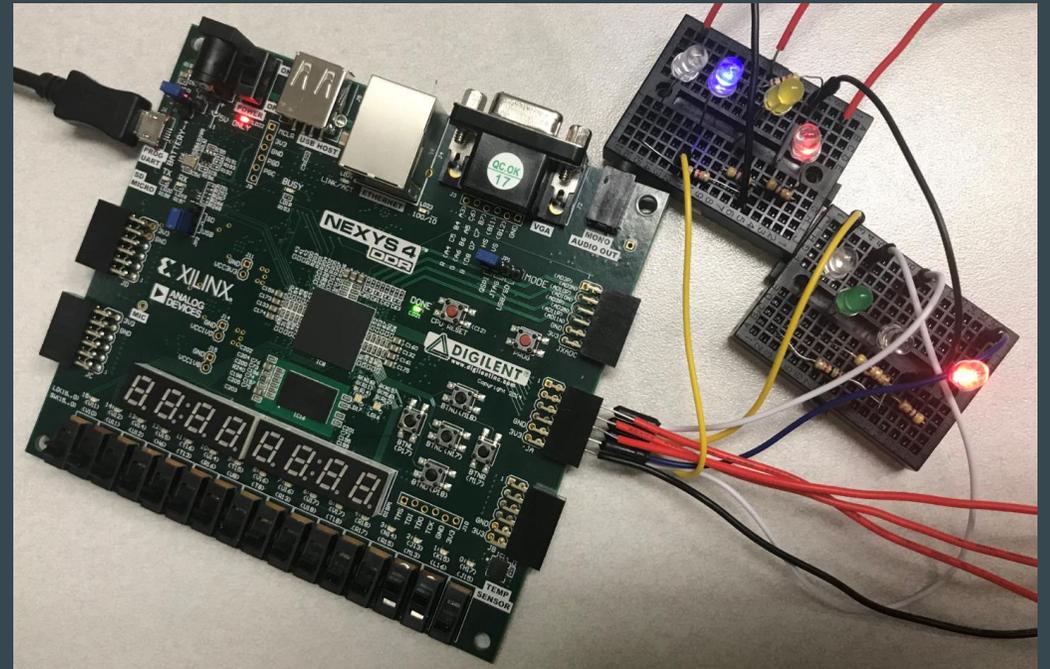
Implementation

- Bread board
 - 5 LEDs each connected to a pull-down resistor
 - Each LED connect to PMOD port (JA & JB)
- Control
 - Rush hour mode enabled by SW0
 - EW crosswalk enabled by SW1
 - NS crosswalk enabled by SW2
 - Secondary road turn enabled by SW3

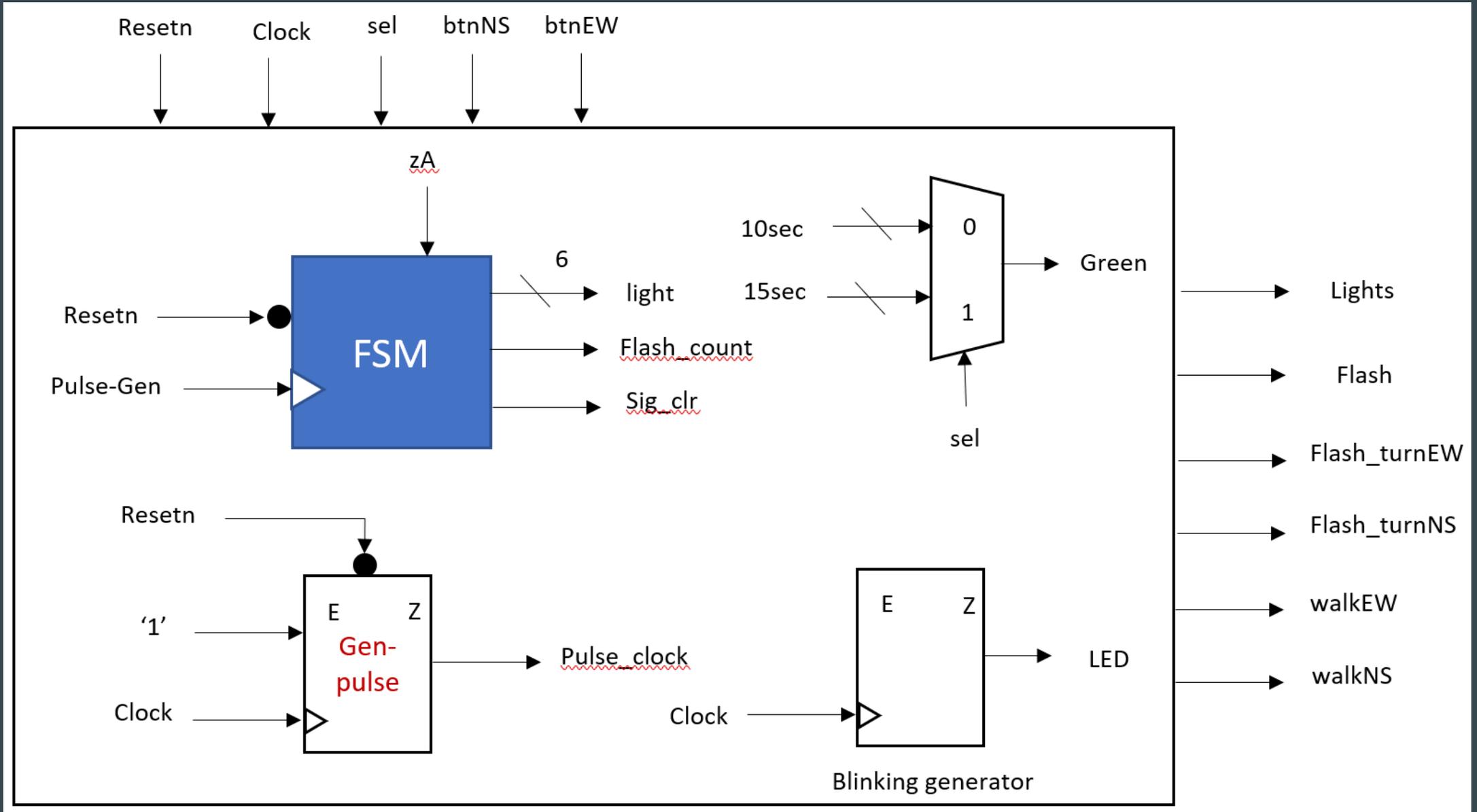


Implementation

- Top file and 2 sub functions
 - Gen pulse function
 - MUX (10 or 15 sec green light)
 - Blinking function for Cross Walk LED
 - Finite State Machine for controlling lights
 - Timing of the light



Top File Design



Blink LED Signal

```
constant max_count : natural := 48000000;  
signal Rst : std_logic;
```

```
-- 0 to max_count counter  
compteur : process(refclk, Rst)  
    variable count : natural range 0 to max_count;  
begin  
    if Rst = '1' then  
        count := 0;  
        led <= '1';  
    elsif rising_edge(refclk) then  
        if count < max_count/2 then  
            count := count + 1;  
            led <= '1';  
        elsif count < max_count then  
            led <= '0';  
            count := count + 1;  
        else  
            led <= '1';  
            count := 0;  
        end if;  
    end if;  
end process compteur;  
  
end struct;
```

Finite State Machine Code

```
99 process (pulse_clk, resetn)
100
101 begin
102     if resetn = '0' then y <= S1;
103         seconds_count <= (others => '0');
104     elsif (pulse_clk'event and pulse_clk = '1') then
105         case y is
106             when S1 =>
107                 if seconds_count < Green_Light_Time then
108                     y <= S1;
109                     seconds_count <= seconds_count + 1;
110                 else
111                     y <= S2;
112                     seconds_count <= (others => '0');
113                 end if;
114
115             when S2 =>
116                 if seconds_count < three_sec then
117                     y <= S2;
118                     seconds_count <= seconds_count + 1;
119                 else
120                     y <= S3;
121                     seconds_count <= (others => '0');
122                 end if;
123
```

```
123
124
125     when S3 =>
126         if seconds_count < one_sec then
127             y <= S3;
128             seconds_count <= seconds_count + 1;
129         else
130             y <= S9;
131             seconds_count <= (others => '0');
132         end if;
133
134     when S4 =>
135         if seconds_count < Green_Light_Time then
136             y <= S4;
137             seconds_count <= seconds_count + 1;
138         else
139             y <= S5;
140             seconds_count <= (others => '0');
141         end if;
142
143     when S5 =>
144         if seconds_count < three_sec then
145             y <= S5;
146             seconds_count <= seconds_count + 1;
147         else
148             y <= S6;
149             seconds_count <= (others => '0');
150         end if;
```

Finite State Machine Output

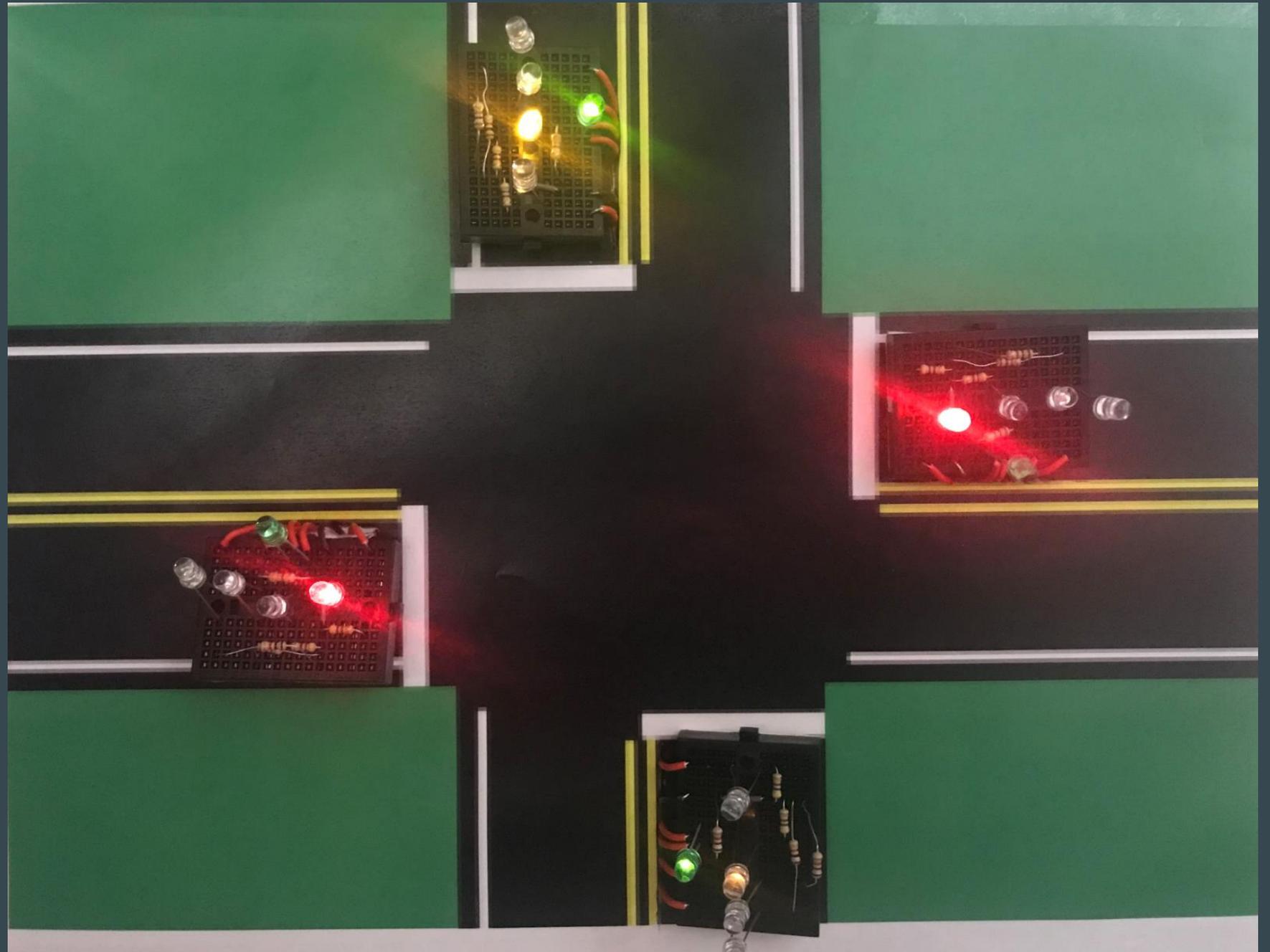
```
Outputs: process (y, seconds_count)
begin
  walkNS <= "0";
  walkEW <= "0";
  flash_turnNS <= '0';
  flash_turnEW <= '0';

  case y is

    when S1 => if btnnoflash = '1' then flash_turnNS <= '0'; lights <= "001100"; else flash_turnNS <= blink_led_turn; lights <= "001100"; end if;
    when S2 => lights <= "001010";
    when S3 => lights <= "001001";
    when S4 => if btnnoflash = '1' then flash_turnEW <= '0'; lights <= "100001"; else flash_turnEW <= blink_led_turn; lights <= "100001"; end if;
    when S5 => lights <= "010001";
    when S6 => lights <= "001001";
    when S7 => walkNS <= "1"; lights <= "001001";
    when S8 => walkEW <= "1"; lights <= "001001";
    when S9 => flash_turnNS <= '1'; lights <= "001001";
    when S10 => flash_turnEW <= '1'; lights <= "001001";
    when S11 => lights <= "001001";
    when S12 => lights <= "001001";
    when S13 => lights <= "001001";
    when S14 => lights <= "001001";
  end case;

end process;
```

Demo



Improvement

Below is the list of some features we would like to add into the system to make it better:

- 1) Detection of traffic volume by adding more logics into the coding and sensors --> More efficient.
- 2) Emergence vehicle detection such as ambulance, police etc...by using wireless sensor network at the signal intersection --> Efficient operation during emergency mode.
- 3) It can give more time to an intersection approach that is experiencing heavy traffic, or shorten or even skip a phase that has little or no traffic waiting for a green light --> Less waiting time.
- 4) Traffic signals are activated to detect the approach of a train near a rail crossing --> Reduce unnecessary stopping and safety.

