

# DIGITAL LOGIC DESIGN

## VHDL Coding for FPGAs

### Unit 6

- ✓ FINITE STATE MACHINES (FSMs)
  - Moore Machines
  - Mealy Machines
  - Algorithmic State Machine (ASM) charts

# ✓ FINITE STATE MACHINES (FSMs)

- VHDL Coding: There exist many different styles. The style explained here considers two processes: one for the state transitions, and another for the outputs.
- First Step: Have your FSM diagram (ASM preferably) ready. The coding then just simply follows the state diagram.
- We need to define a custom user data type (e.g., "state") to represent the states

```
type state is (S1, S2, ... S10) - example with 10 states
signal y: state;
```

We then define a signal of type "state" (e.g. 'y'). In the example, this signal can only take values from S1 to S10.

- Two processes must be considered (see figure on next slide)
  - ✓ *Transitions*: It is where the state transitions (that occur on the clock edge) are described.
  - ✓ *Outputs*: This is a combinational circuit where outputs are defined based on the current state and input signals.

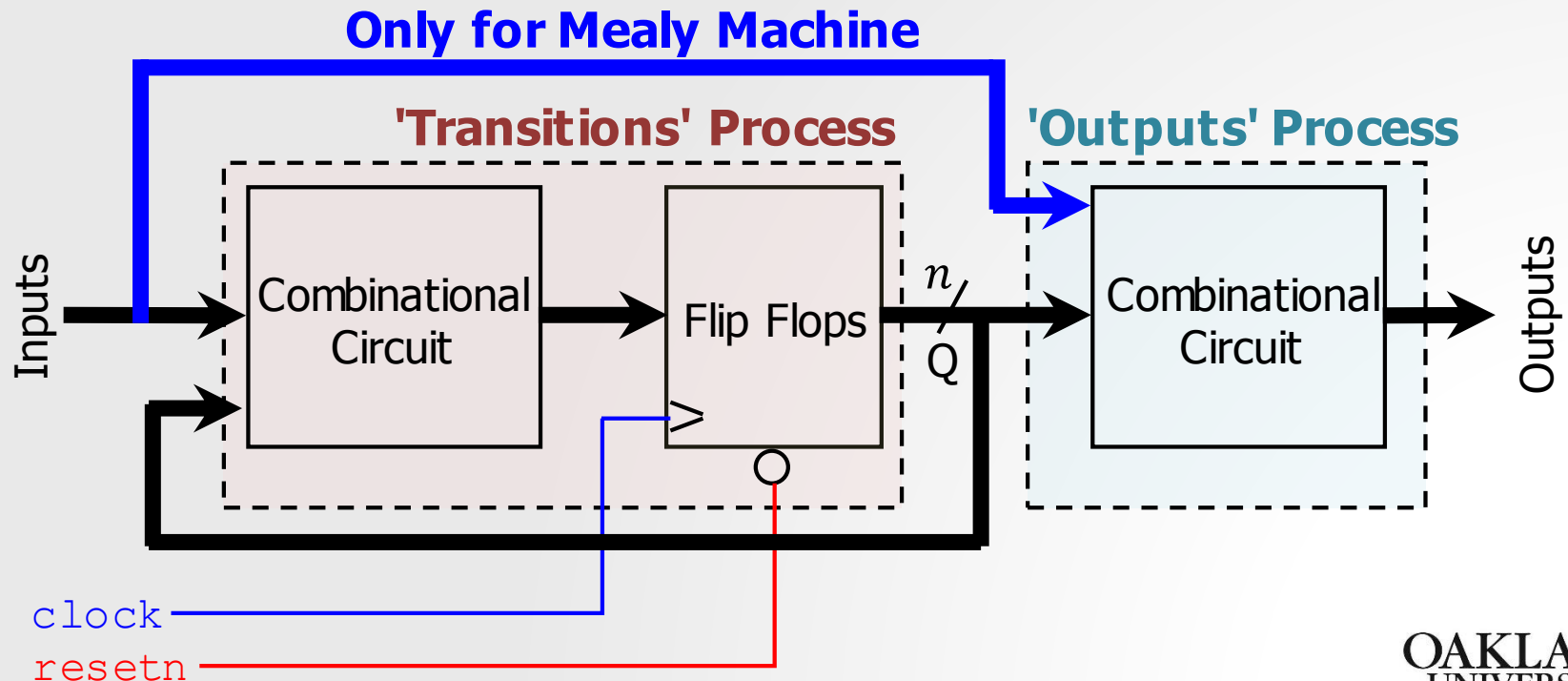
# ✓ FINITE STATE MACHINES (FSMs)

- Classification:

**Moore FSM:** Outputs depend only on the current state of the circuit.

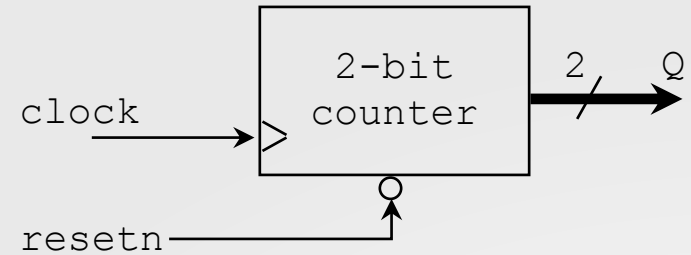
**Mealy FSM:** Outputs depend on the current state of the circuit as well as the inputs of the circuit.

- There should be a *'resetn'* signal so that the FSM always start from an initial state. The figure depicts a generic state machine with the VHDL processes that describe it.



# ✓ Example: 2-bit counter

- Moore-type FSM
- Count: 00 → 01 → 10 → 10 → 00 ...



```
library ieee;
use ieee.std_logic_1164.all;
```

```
entity my_2bitcounter is
  port ( clock, resetn: in std_logic;
        Q: out std_logic_vector (1 downto 0));
end my_2bitcounter;
```

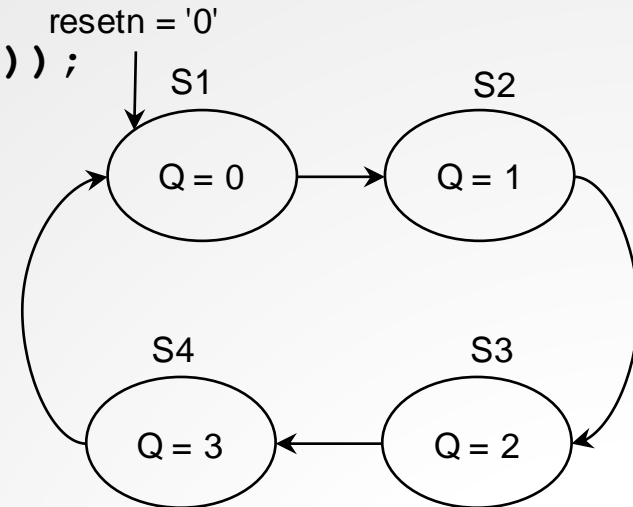
```
architecture bhv of my_2bitcounter is
```

```
type state is (S1, S2, S3, S4);
signal y: state;
```

```
begin
```

```
Transitions: process (resetn, clock)
begin
  if resetn = '0' then -- asynchronous signal
    y <= S1; -- initial state
```

Custom datatype definition: 'state' with 4 possible values: S1 to S4



Definition of signal 'y' of type 'state'.

Process that defines the state transitions

# ✓ Example: 2-bit counter

```
...  
    elsif (clock'event and clock='1') then  
        case y is  
            when S1 => y <= S2;  
            when S2 => y <= S3;  
            when S3 => y <= S4;  
            when S4 => y <= S1;  
        end case;  
    end if;  
end process;
```

Process that defines the state transitions.

Note that the state transitions only occur on the rising clock edge

```
Outputs: process (y)  
begin  
    case y is  
        when S1 => Q <= "00";  
        when S2 => Q <= "01";  
        when S3 => Q <= "10";  
        when S4 => Q <= "11";  
    end case;  
end process;  
end bhv;
```

Note that the outputs only depend on the current state, hence this is a Moore machine

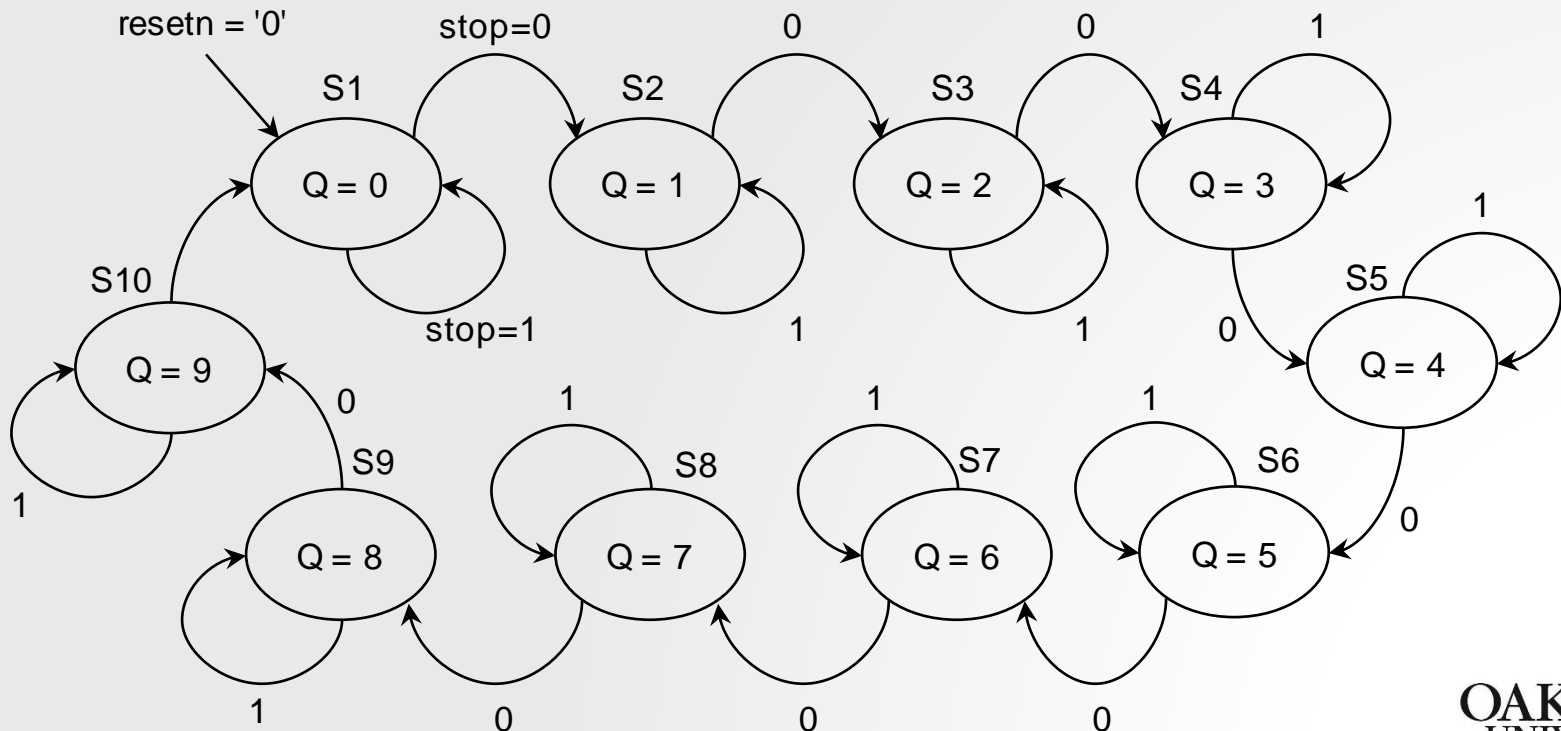
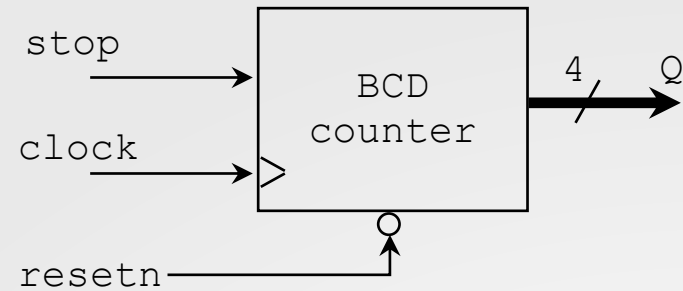
Process that defines the outputs.

Note that the output is not controlled by the clock edge, only by the current state

➤ **my\_2bitcounter.zip:**  
my\_2bitcounter.vhd,  
tb\_my\_2bitcounter.vhd

# ✓ Example: BCD counter with stop signal

- Moore-type FSM
- If the 'stop' signal is asserted, the count stops. If 'stop' is not asserted, the count continues.



# ✓ BCD Counter with stop signal

- VHDL code: Moore FSM

```
library ieee;  
use ieee.std_logic_1164.all;
```

```
entity bcd_count is  
  port ( clock, resetn, stop: in std_logic;  
        Q: out std_logic_vector (3 downto 0));  
end bcd_count;
```

```
architecture bhv of bcd_count is
```

Custom datatype definition: 'state'  
with 10 possible values: S1 to S10

```
type state is (S1, S2, S3, S4, S5, S6, S7, S8, S9, S10);
```

```
signal y: state;
```

Definition of signal 'y' of type 'state'.

```
begin
```

```
Transitions: process (resetn, clock, stop)
```

```
begin
```

```
  if resetn = '0' then -- asynchronous signal  
    y <= S1; -- initial state
```

Process that  
defines the  
state transitions

```
...
elsif (clock'event and clock='1') then
  case y is
    when S1 =>
      if stop='1' then y<=S1; else y<=S2; end if;
    when S2 =>
      if stop='1' then y<=S2; else y<=S3; end if;
    when S3 =>
      if stop='1' then y<=S3; else y<=S4; end if;
    when S4 =>
      if stop='1' then y<=S4; else y<=S5; end if;
    when S5 =>
      if stop='1' then y<=S5; else y<=S6; end if;
    when S6 =>
      if stop='1' then y<=S6; else y<=S7; end if;
    when S7 =>
      if stop='1' then y<=S7; else y<=S8; end if;
    when S8 =>
      if stop='1' then y<=S8; else y<=S9; end if;
    when S9 =>
      if stop='1' then y<=S9; else y<=S10; end if;
    when S10 =>
      if stop='1' then y<=S10; else y<=S1; end if;
  end case;
end if;
end process;
...
```

Note that the state transitions depend on the stop signal 'stop'

Process that defines the state transitions

Note that the state transitions only occur on the rising clock edge



# ✓ BCD Counter with stop signal

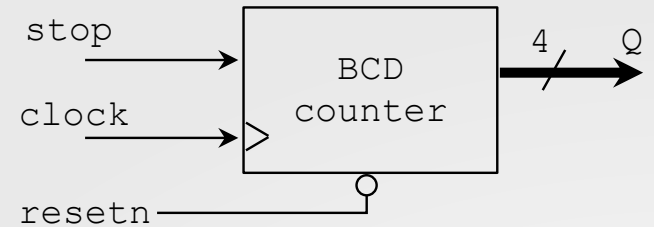
- VHDL code:

...

```

Outputs: process (y)
begin
    case y is
        when S1 => Q <= "0000";
        when S2 => Q <= "0001";
        when S3 => Q <= "0010";
        when S4 => Q <= "0011";
        when S5 => Q <= "0100";
        when S6 => Q <= "0101";
        when S7 => Q <= "0110";
        when S8 => Q <= "0111";
        when S9 => Q <= "1000";
        when S10 => Q <= "1001";
    end case;
end process;
end bhv;

```



Note that the outputs only depend on the current state, hence this is a Moore machine

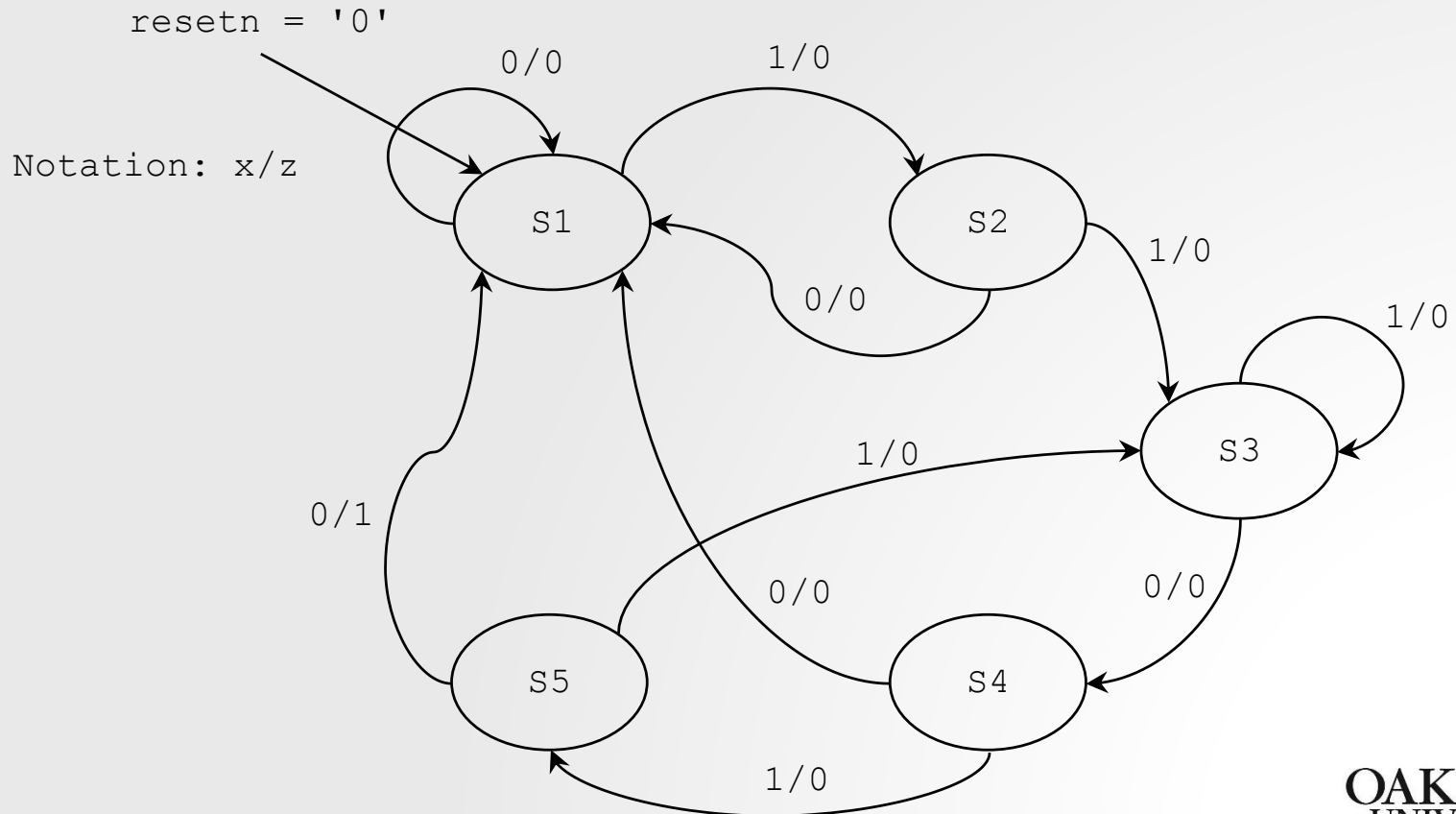
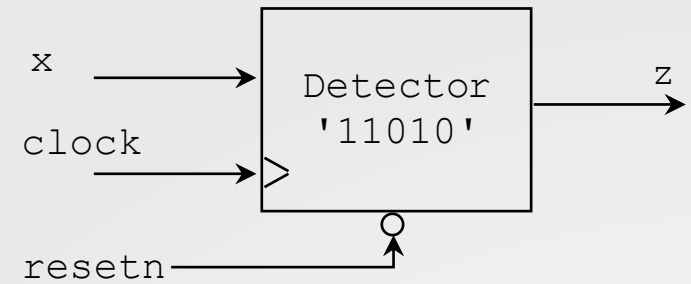
Process that defines the outputs

Note that the output is not controlled by the rising clock edge, only by the current state.

- `bcd_count.zip:`  
`bcd_count.vhd,`  
`tb_bcd_count.vhd`

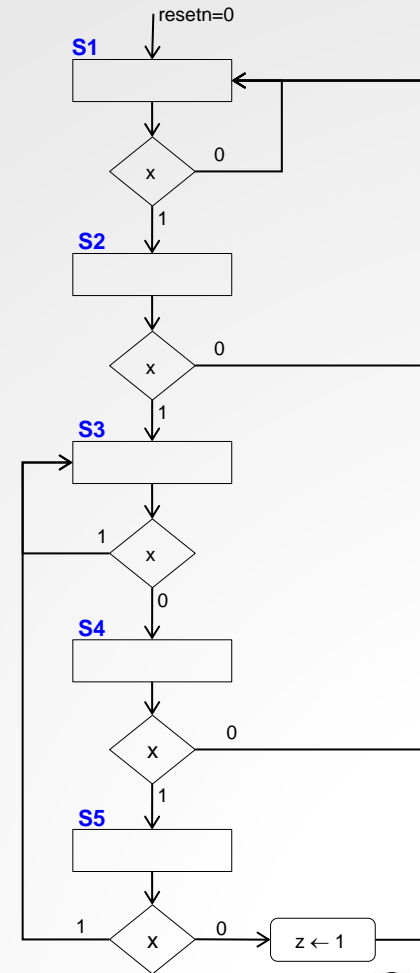
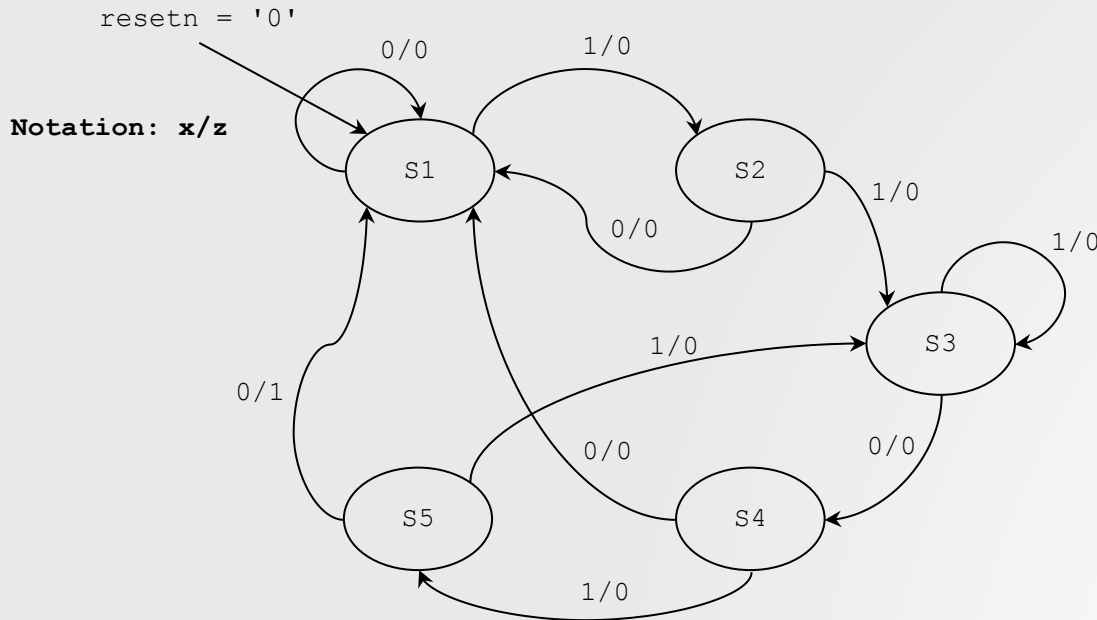
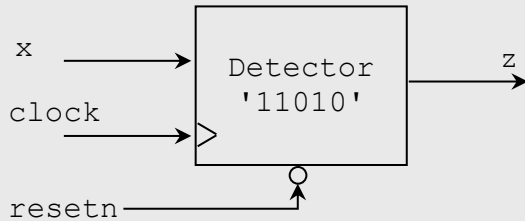
# ✓ Example: Sequence detector with overlap

- Mealy-type FSM
- It detects the sequence 11010
- State Diagram: 5 states



# ✓ ALGORITHMIC STATE MACHINE (ASMs) charts

- This is an efficient way to represent Finite State Machines.
- We use the 11010 detector as an example here.



# ✓ Example: Sequence detector with overlap

- VHDL Code: Mealy FSM

```
library ieee;
use ieee.std_logic_1164.all;
```

```
entity my_seq_detect is
  port ( clock, resetn, x: in std_logic;
        z: out std_logic );
end my_seq_detect;
```

```
architecture bhv of my_seq_detect is
```

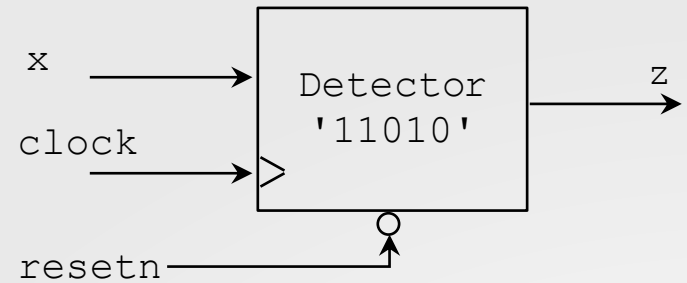
```
  type state is (S1, S2, S3, S4, S5);
```

```
  signal y: state;
```

```
begin
```

```
  Transitions: process (resetn, clock, x)
  begin
    if resetn = '0' then -- asynchronous signal
      y <= S1; -- initial state
```

Process that defines the state transitions

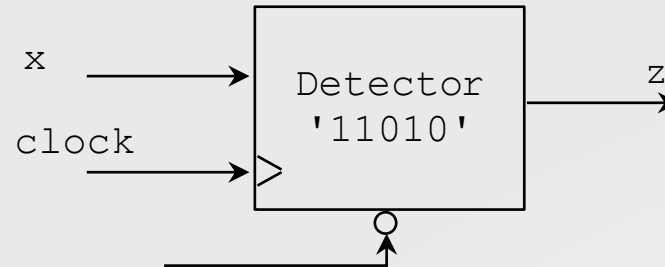


Custom datatype definition: 'state' with 5 possible values: S1 to S5

Definition of signal 'y' of type 'state'.

# ✓ Example: Sequence detector with overlap

- VHDL Code: Mealy FSM



...

```

elsif (clock'event and clock='1') then
  case y is
    when S1 =>
      if x = '1' then y<=S2; else y<=S1; end if;
    when S2 =>
      if x = '1' then y<=S3; else y<=S1; end if;
    when S3 =>
      if x = '1' then y<=S3; else y<=S4; end if;
    when S4 =>
      if x = '1' then y<=S5; else y<=S1; end if;
    when S5 =>
      if x = '1' then y<=S3; else y<=S1; end if;
  end case;
end if;
end process;

```

...

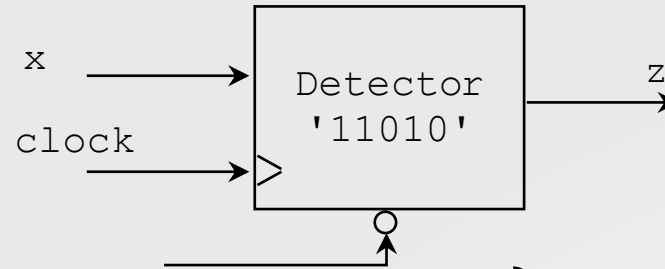
Note that the state transitions depend on the input signal 'x'

Process that defines the state transitions

Note that the state transitions only occur on the rising clock edge

# ✓ Example: Sequence detector with overlap

- VHDL Code: Mealy FSM



...

Outputs: process (x, y)

begin

z <= '0' ;

case y is

when S1 =>

when S2 =>

when S3 =>

when S4 =>

when S5 =>

**if x = '0' then z <= '1' ; end if ;**

end case ;

end process ;

end bhv ;

Setting default values. If the value of z is not declared at some point in the case statement, z is set to 0.

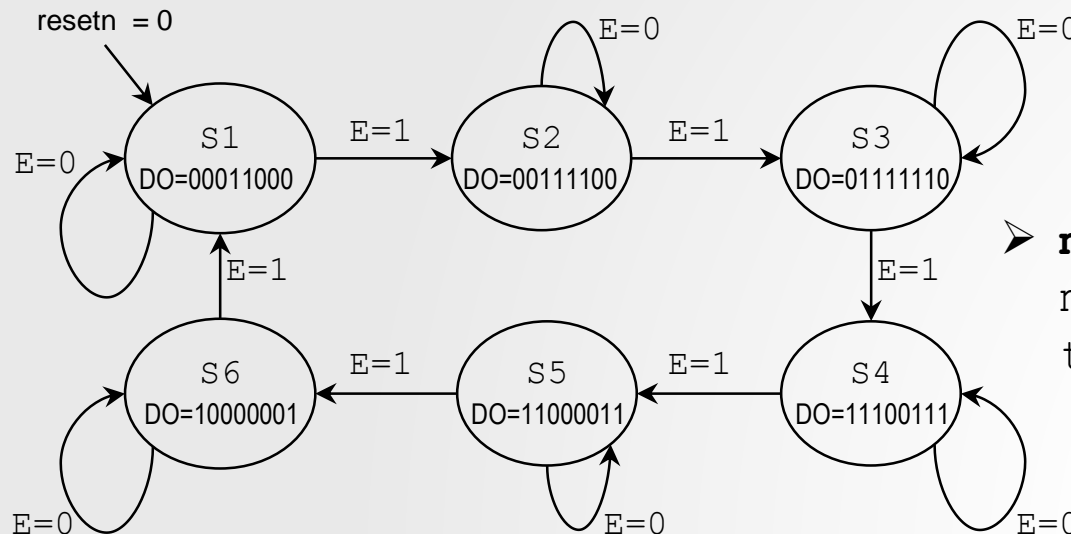
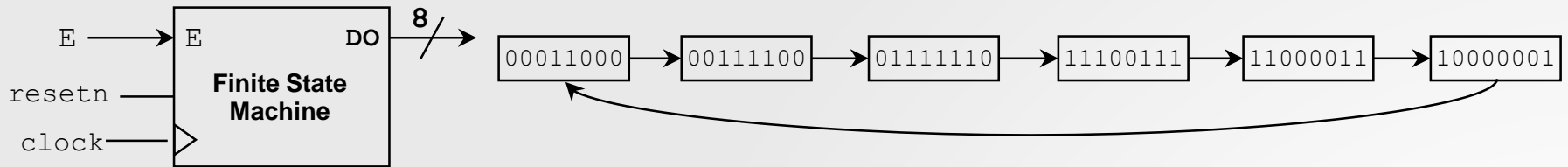
Note that the output depends on the current state and the input 'x', hence this is a Mealy machine.

Process that defines the outputs

- **my\_seq\_detect.zip:**  
my\_seq\_detect.vhd,  
tb\_my\_seq\_detect.vhd

# ✓ Example: LED sequence

- Moore-type FSM
- Sequence: 0001100, 00111100, 01111110, 11100111, 11000011, 10000001.
- The FSM includes an enable that allows for state transitions.
- This FSM requires 6 states, i.e. 3 flip flops. The 6-bit output is generated by a combinational circuit (decoder).



➤ **my\_ledseq.zip:**  
 my\_ledseq.vhd,  
 tb\_my\_ledseq.vhd